

ECE 8101: Nonconvex Optimization for Machine Learning

Lecture Note 3-2: Decentralized Optimization for Learning

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Outline

In this lecture:

- Key Idea of Decentralized Nonconvex Optimization for Learning
- Representative Techniques
- Convergence Results

Revisit the Distributed/Federated Learning Problem

- Consider the problem:

$$\min_{\mathbf{x} \in \mathbb{R}^m} f(\mathbf{x}) \triangleq \min_{\mathbf{x} \in \mathbb{R}^d} \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x}),$$

where $f_i(\mathbf{x}) \triangleq \mathbb{E}_{\xi_i \sim \mathcal{D}_i} [F_i(\mathbf{x}, \xi_i)]$ is nonconvex

- **Distributed/Federated Learning:** The “summation” in the mini-batched SGD, which implies a **decomposable** and **distributed** implementation:
 - ▶ Each stochastic gradient $\nabla F(\mathbf{x}_k, \xi_i)$ can be computed by a “worker/client” i
 - ▶ B_k workers can compute such stochastic gradients **in parallel**
 - ▶ A **server** collects the stochastic gradients returned by workers and **aggregate**

But what if we don't have a server?

Reasons for “Not Having a Server” in Distributed Learning

- Networks Having No Infrastructure

- ▶ Networking protocols based on random access (CSMA, ALOHA, etc.)
- ▶ Ad hoc sensor networks for environmental monitoring
- ▶ Multi-agent systems (autonomous driving, UAVs/UGVs, robotics, etc.)
- ▶ Autonomous swarms on battle field
- ▶ In-situ disaster recovery

- Security/Robustness/Privacy Concerns

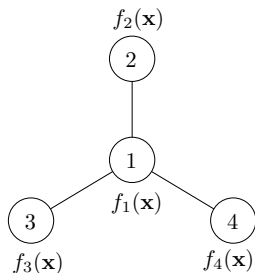
- ▶ Avoid single point of failure
- ▶ Avoid having a single target under cyber-attacks
- ▶ Avoid communication/networking bottleneck
- ▶ Need for information privacy preservation
- ▶ Need for decentralization to avoid being controlled by a single party

- Economics Motivations

- ▶ Competition/collaboration among entities
- ▶ Build trust between multiple parties
- ▶ Fairness guarantees
- ▶ Promote personalization and diversity...

Decentralization Optimization for Learning: The Setup

- A network represented by a **connected** graph $\mathcal{G} = (\mathcal{N}, \mathcal{L})$, with $|\mathcal{N}| = N$, $|\mathcal{L}| = L$
- $\mathbf{x} \in \mathbb{R}^d$: a **global** learning model
- Each node/agent i can only evaluate a local objective function $f_i(\mathbf{x}) \triangleq \mathbb{E}_{\xi_i \sim \mathcal{D}_i} [F_i(\mathbf{x}, \xi_i)]$
- Global objective function is: $\frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$
- **Goal:** To learn the global model **collaboratively in a decentralized fashion** (i.e., w/o needing any server)



Example: Decentralized Learning in Multi-Agent Systems

- A multi-agent system (drones, robots, soldiers, etc.). Each agent collects high-resolution images $\{\mathbf{u}_{ij}, \mathbf{v}_{ij}, \theta_{ij}\}_{j=1}^{N_i}$
- $\mathbf{u}_{ij}, \mathbf{v}_{ij}, \theta_{ij}$: pixels, geographical information, ground-truth label of the j -th image at agent i .
- Agents **collaboratively** perform image regression based on linear model with parameters $\mathbf{x} = [\mathbf{x}_1^\top \mathbf{x}_2^\top]^\top$
- This problem can be written as: $\min_{\mathbf{x}} f(\mathbf{x}) \triangleq \min_{\mathbf{x}} \sum_{i=1}^N f_i(\mathbf{x})$, where $f_i(\mathbf{x}) \triangleq \frac{1}{N_i} \sum_{j=1}^{N_i} (\theta_{ij} - \mathbf{u}_{ij}^\top \mathbf{x}_1 - \mathbf{v}_{ij}^\top \mathbf{x}_2)^2$



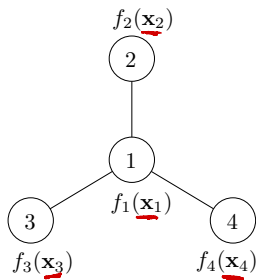
Consensus Reformulation: The First Step

- **Goal:** To solve the following optimization problem **distributively & collaboratively**

$$\min_{\mathbf{x} \in \mathbb{R}^d} f(\mathbf{x}) = \min_{\mathbf{x} \in \mathbb{R}^d} \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$$

- Clearly, this problem can be rewritten in a **consensus** form:

$$\min_{\mathbf{x}_i \in \mathbb{R}^d, \forall i} \left\{ \frac{1}{N} \sum_{i=1}^N \overset{\text{local}}{\underbrace{f_i(\mathbf{x}_i)}} \mid \underbrace{\mathbf{x}_i = \mathbf{x}_j, \forall (i, j) \in \mathcal{L}} \right\}$$



The consensus reformulation shares the same spirit with **distributed/federated learning** that each node maintains a **local copy** of the global model

Recall What We Did When We Have a Server

- In **distributed/federated learning**: Each node/client i computes

$$\mathbf{x}_{i,k+1} = \bar{\mathbf{x}}_k - s_k \mathbf{g}_{i,k}$$

where $\bar{\mathbf{x}}_k \triangleq \frac{1}{N} \sum_{i=1}^N \mathbf{x}_{i,k}$ is the node/client average in iteration k

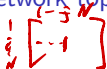
- This prompts the following **natural idea** for decentralized learning

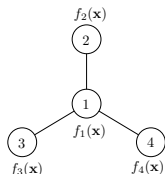
$$\mathbf{x}_{i,k+1} = \text{"Some approximation of } \bar{\mathbf{x}}_k \text{"} - s_k \mathbf{g}_{i,k}$$

- This idea turns out to be the foundation of **decentralized consensus optimization**
 - ▶ **Note**: This is an insight in hindsight. Decentralized consensus optimization traces its roots to the seminal work [Tsitsiklis, Ph.D. Thesis@MIT, 1984]!

A Decentralized Method for Computing Average

Consider a **consensus matrix** $\mathbf{W} \in \mathbb{R}^{N \times N}$ that satisfies:

- **Doubly stochastic**: $\sum_{i=1}^N [\mathbf{W}]_{ij} = \sum_{j=1}^N [\mathbf{W}]_{ij} = 1$.
- Sparsity pattern defined by **network topology**: $[\mathbf{W}]_{ij} > 0$ for $\forall (i, j) \in \mathcal{L}$ and $[\mathbf{W}]_{ij} = 0$ otherwise

- **Symmetric** and hence **real** eigenvalues in $(-1, 1]$ (thus can be **sorted**).
Moreover, easy to see that $\lambda_{\max} = 1$ with corresponding eigenvector $\mathbf{1}_N$.
- W.l.o.g., denote eigenvalues as $-1 < \lambda_N \leq \dots \leq \lambda_1 = 1$. Let $\beta \triangleq \max\{|\lambda_2|, |\lambda_N|\}$ (i.e., **2nd-largest eigenvalue in magnitude**).



$$\mathbf{W} = \begin{bmatrix} 1/4 & 1/4 & 1/4 & 1/4 \\ 1/4 & 3/4 & 0 & 0 \\ 1/4 & 0 & 3/4 & 0 \\ 1/4 & 0 & 0 & 3/4 \end{bmatrix}$$

A Decentralized Method for Computing Average

- 1 $k = 0$. Each node has initial value $\mathbf{x}_{i,0}$ to be averaged with other nodes
- 2 In k -th iteration: Each node shares its local copy to its neighbors.
- 3 Upon reception of all local copies from its neighbors, each node performs the local updates:

$$\mathbf{x}_{i,k+1} = \sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k},$$

where $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$.

- 4 Let $k \leftarrow k + 1$ and go to Step 2

A Decentralized Method for Computing Average

- Define a stacked matrix of all local copies:

$$\mathbf{X}_k \triangleq \begin{bmatrix} \mathbf{x}_{1,k} & \mathbf{x}_{2,k} & \cdots & \mathbf{x}_{N,k} \end{bmatrix} \in \mathbb{R}^{d \times N}.$$

- Then the algorithm in the previous slide can be compactly written as

$$\mathbf{X}_{k+1} = \mathbf{X}_k \mathbf{W}, \quad \mathbf{X}_{k+1}^\top = \mathbf{W}_2^\top \mathbf{X}_k^\top$$

(i.e., $\mathbf{X}_k = \mathbf{X}_0 \mathbf{W}^k$). Similar to a discrete-time finite-state Markov chain.

Perron-Frobenius Thm

- Fact:** The stationary distribution of an irreducible aperiodic finite-state Markov chain is uniform iff its transition matrix is doubly stochastic.
- Convergence rate of "averaging": Let $\mathbf{W}^\infty = \lim_{k \rightarrow \infty} \mathbf{W}^k$. Then, we have $\mathbf{W}^\infty = \frac{1}{N} \mathbf{1}_N \mathbf{1}_N^\top$. Further, it holds that

$$\left[\begin{array}{ccc} \frac{1}{N} & \cdots & \frac{1}{N} \\ \vdots & \ddots & \vdots \\ \frac{1}{N} & \cdots & \frac{1}{N} \end{array} \right] \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \quad \left\| \mathbf{W}^\infty \mathbf{e}_i - \mathbf{W}^k \mathbf{e}_i \right\|^2 \leq \beta^{2k}, \quad \forall i \in \{1, \dots, N\}, k \in \mathbb{N}.$$

*↑
ith basis vector in \mathbb{R}^d .*

$\frac{\lambda_2}{\lambda_1}$

WTS: $\| \underbrace{\frac{1}{N} \mathbb{1}_N}_{\underline{W}^\infty} \underline{e}_i - \underline{W}^k \underline{e}_i \|^2 \leq \beta^{2k}$ ← Lemma.

Proof. $\| \underline{W}^\infty \underline{e}_i - \underline{W}^k \underline{e}_i \|^2 = \| (\underline{W}^\infty - \underline{W}^k) \underline{e}_i \|^2$
 $\leq \underbrace{\| \underline{W}^\infty - \underline{W}^k \|^2}_{\text{induced norm}} \cdot \| \underline{e}_i \|^2 = \| \underline{W}^\infty - \underline{W}^k \|^2$ (1).

Note that \underline{W} is symmetric \Rightarrow It has real eigenvalues.

$\underline{W} = \underline{U} \underline{\Lambda} \underline{U}^T$, where $\underline{\Lambda} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_N \end{bmatrix}$, $\underline{U} = \begin{bmatrix} | & & | \\ \underline{u}_1 & \dots & \underline{u}_N \\ | & & | \end{bmatrix}$
 † Unitary, $\underline{U}^T \underline{U} = \underline{U} \underline{U}^T = \underline{I}$

So, $\underline{W}^k = \underbrace{\underline{U} \underline{\Lambda} \underline{U}^T \cdot \underline{U} \underline{\Lambda} \underline{U}^T \cdot \dots \cdot \underline{U} \underline{\Lambda} \underline{U}^T}_{k \text{ terms}} = \underline{U} \underline{\Lambda}^k \underline{U}^T$ $\begin{bmatrix} \lambda_1^k & & \\ & \ddots & \\ & & \lambda_N^k \end{bmatrix}$

Also, $\underline{W}^\infty = \frac{1}{N} \mathbb{1} \mathbb{1}^T$. clearly, it has one eigenvalue 1 and eigenvector

$\underline{1}_N$. $\underline{W}^\infty = \underline{U}^T \begin{bmatrix} 1 & & \\ & \ddots & \\ & & 0 \end{bmatrix} \underline{U}$ $\sum_{i=1}^N \lambda_i \underline{u}_i \underline{u}_i^T$

(1) = $\| \underline{U} \left(\begin{bmatrix} 1 & & \\ & \ddots & \\ & & 0 \end{bmatrix} - \begin{bmatrix} 1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_N \end{bmatrix} \right) \underline{U}^T \|^2 = \left\| \sum_{i=2}^N \lambda_i \underline{u}_i \underline{u}_i^T \right\|^2$

$\leq \beta^{2k} \left\| \sum_{i=1}^N \lambda_i \underline{u}_i \underline{u}_i^T \right\|^2 = \beta^{2k} \underbrace{\| \underline{U} \underline{U}^T \|^2}_{= \underline{I}} = \beta^{2k}$. □

↑
 replace $\lambda_i \underline{u}_i \underline{u}_i^T$
 by β , factor it
 out, adding $\beta \underline{U} \underline{U}^T$

Decentralized Stochastic Gradient Descent (DSGD)

The DSGD algorithm [Nedic and Ozdaglar, TAC'09]:

DGD
PGD } DSGD.
P-SGD

1 Initialization: Let $k = 1$. Choose initial values for $\mathbf{x}_{i,1}$ and step-size s_1 .

2 In k -th iteration: Each node sends its local copy to its neighbors.

3 Upon reception of all local copies from its neighbors, each node updates its local copy:

$$\mathbf{x}_{i,k+1} = \underbrace{\sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k}}_{\text{Avg consensus step}} - \underbrace{s_k \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k})}_{\text{Local SGD step}}$$

"some approx. $\bar{\xi}_k$ " (pointing to $\xi_{i,k}$)
run this multi-steps. (pointing to ∇F_i)

where $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$.

4 Let $k \leftarrow k + 1$ and go to Step 2

DGD
can be done
of "rounds".

Convergence Results of DSGD

Assumptions:

- $f_i(\cdot)$, $\forall i$ are L -smooth
- Unbiased stochastic gradients: $\mathbb{E}_{\xi_{i,k} \sim \mathcal{D}_i}[\nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k})] = \nabla f_i(\mathbf{x}_{i,k})$, $\forall i, k$
- Bounded local stochastic gradient variance:

$$\mathbb{E}[\|\nabla F_i(\mathbf{x}, \xi) - \nabla f_i(\mathbf{x})\|^2] \leq \sigma^2, \quad \forall i, \mathbf{x}$$

- Bounded gradient dissimilarity: *means $\nabla f_i(\mathbf{x})$ still follows \mathcal{D}_i*

$$\mathbb{E}_{i \sim \mathcal{U}([n])}[\|\nabla f_i(\mathbf{x}) - \nabla f(\mathbf{x})\|^2] \leq \zeta^2, \quad \forall \mathbf{x}$$

- Start from $\mathbf{0}$: $\mathbf{X}_0 = \mathbf{0}$ (not necessary, but simplifies the proof w.l.o.g.)

Convergence Results of DSGD

- Let $s_k = s, \forall k$, and define two constants:

$$D_1 := \left(\frac{1}{2} - \frac{9s^2 L^2 N}{(1-\beta)^2 D_2} \right), \text{ and } D_2 := \left(1 - \frac{18s^2}{(1-\beta)^2} N L^2 \right)$$

Theorem 1 ([Lian et al. NeurIPS'17])

$\left[\begin{matrix} \vdots \\ \nabla f_1(z_{1k}) \\ \vdots \\ \vdots \\ \nabla f_N(z_{Nk}) \\ \vdots \end{matrix} \right]_{\text{d.w.}}$

Under the stated assumptions, the following convergence rate holds for DSGD:

$$\begin{aligned} & \frac{1}{K} \left(\frac{1-sL}{2} \sum_{k=0}^{K-1} \mathbb{E} \left[\left\| \frac{\nabla f(\mathbf{X}_k) \mathbf{1}_N}{N} \right\|^2 \right] + D_1 \sum_{k=0}^{K-1} \mathbb{E} \left[\left\| \nabla f \left(\frac{\mathbf{X}_k \mathbf{1}_N}{N} \right) \right\|^2 \right] \right) \\ & \leq \underbrace{\frac{f(\mathbf{0}) - f^*}{sK}}_{\text{d.w.}} + \frac{sL}{2N} \sigma^2 + \frac{s^2 L^2 N \sigma^2}{(1-\beta)^2 D_2} + \frac{9s^2 L^2 N \zeta^2}{(1-\beta)^2 D_2} \end{aligned}$$

$= O\left(\frac{1}{K}\right)$ to some error ball.

$\bar{z}_k \triangleq \frac{1}{N} \sum_{i=1}^N z_{ik}$

Convergence Results of DSGD

Corollary 2 ([Lian et al. NeurIPS'17])

Under the same assumptions as in Theorem 1, if $s = \frac{1}{2L + \sigma\sqrt{K/N}}$, then DSGD achieves the following convergence rate:

$$\frac{1}{K} \sum_{k=0}^{K-1} \mathbb{E} \left[\left\| \nabla f \left(\frac{\mathbf{X}_k \mathbf{1}_N}{N} \right) \right\|^2 \right] \leq \frac{8(f(\mathbf{0}) - f^*)}{K} + \frac{(8f(\mathbf{0}) - 8f^* + 4L)}{\sqrt{KN}}.$$

Remark 1

If K is sufficiently large such that

$$K \geq \frac{4L^4 N^5}{\sigma^2 (f(\mathbf{0}) - f^* + L)^2} \left(\frac{\sigma^2}{1 - \beta^2} + \frac{9\zeta^2}{(1 - \beta)^2} \right) \text{ and } K \geq \frac{72L^2 N^2}{\sigma^2 (1 - \beta)^2},$$

then the convergence rate of DSGD is $O\left(\frac{1}{K} + \frac{1}{\sqrt{NK}}\right)$. ← linear speedup

Convergence Results of DSGD

Theorem 3 ([Lian et al. NeurIPS'17])

With $s = \frac{1}{2L + \sigma\sqrt{K/N}}$ and under the same assumptions in Theorem 1, it holds that

$$\frac{1}{KN} \mathbb{E} \left[\sum_{k=0}^{K-1} \sum_{i=1}^N \left\| \frac{\sum_{i'=1}^N \mathbf{x}_{i',k}}{N} - \mathbf{x}_{i,k} \right\|^2 \right] \leq N s^2 \frac{A}{D_2},$$

where the constant A is defined as:

$$A := \frac{2\sigma^2}{1-\beta^2} + \frac{18\zeta^2}{(1-\beta)^2} + \frac{L^2}{D_1} \left(\frac{\sigma^2}{1-\beta^2} + \frac{9\zeta^2}{(1-\beta)^2} \right) + \frac{18}{(1-\beta)^2} \left(\frac{f(\mathbf{0}) - f^*}{sK} + \frac{sL\sigma^2}{2ND_1} \right).$$

Remark 2

The local copies achieve consensus at the rate $O(1/K)$

Preparation:

$$\underline{X}_{=k} \triangleq \begin{bmatrix} \vdots & & \vdots \\ x_{1,k} & \dots & x_{N,k} \\ \vdots & & \vdots \end{bmatrix}_{d \times N}, \quad \underline{W} \triangleq \begin{bmatrix} w_{11} & \dots & w_{1N} \\ \vdots & & \vdots \\ w_{M1} & \dots & w_{MN} \end{bmatrix}_{N \times N}, \quad \partial \underline{F}(\underline{X}_{=k}, \underline{\xi}_{=k}) \triangleq \begin{bmatrix} \partial F_1(x_{1,k}, \xi_{1,k}) & \dots & \partial F_N(x_{N,k}, \xi_{N,k}) \\ \vdots & & \vdots \end{bmatrix}_{d \times N}$$

Recall: $x_{i,k+1} = \sum_{j=1}^N [W]_{ij} x_{j,k} - s \nabla F_i(x_{i,k}, \xi_{i,k}), \forall i$

Concatenating $x_{i,k+1}, \forall i$, we have:

$$\begin{bmatrix} \vdots & & \vdots \\ x_{1,k+1} & \dots & x_{N,k+1} \\ \vdots & & \vdots \end{bmatrix} = \begin{bmatrix} \vdots & & \vdots \\ x_{1,k} & \dots & x_{N,k} \\ \vdots & & \vdots \end{bmatrix} \begin{bmatrix} w_{11} & \dots & w_{1N} \\ \vdots & & \vdots \\ w_{M1} & \dots & w_{MN} \end{bmatrix} - s \begin{bmatrix} \partial F_1(x_{1,k}, \xi_{1,k}) & \dots & \partial F_N(x_{N,k}, \xi_{N,k}) \\ \vdots & & \vdots \end{bmatrix}$$

In matrix form: $\underline{X}_{=k+1} = \underline{X}_{=k} \underline{W} - s \partial \underline{F}(\underline{X}_{=k}, \underline{\xi}_{=k})$

$$\Rightarrow \frac{1}{N} \underline{X}_{=k+1} \mathbf{1}_N = \frac{1}{N} \underline{X}_{=k} \underline{W} \mathbf{1}_N - \frac{s}{N} \partial \underline{F}(\underline{X}_{=k}, \underline{\xi}_{=k}) \mathbf{1}_N$$

$$\Rightarrow \bar{x}_{k+1} = \bar{x}_k - \frac{s}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})$$

Proof of Thm 1: From descent lemma, "G"

$$\mathbb{E}[f(\bar{x}_{k+1})] = \mathbb{E}\left[f\left(\bar{x}_k - \frac{s}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})\right)\right]$$

$$\leq \mathbb{E}[f(\bar{x}_k)] - \frac{s}{N} \mathbb{E}\left[\nabla f(\bar{x}_k)^T \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})\right] + \frac{s^2}{2} \mathbb{E}\left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k}) \right\|^2\right]$$

Consider the quad term:

$$\mathbb{E}\left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k}) \right\|^2\right] \stackrel{\text{tr}}{=} \mathbb{E}\left[\left\| \frac{1}{N} \left(\sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k}) - \sum_{i=1}^N \nabla f_i(x_{i,k}) \right) + \frac{1}{N} \sum_{i=1}^N \nabla f_i(x_{i,k}) \right\|^2\right]$$

$$= \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) - \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right] + \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right]$$

$$\Rightarrow \mathbb{E}[f(\bar{\mathbf{x}}_{k+1})] \leq \mathbb{E}[f(\bar{\mathbf{x}}_k)] - \frac{s}{N} \mathbb{E} \left[\nabla f(\bar{\mathbf{x}}_k)^T \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) \right] +$$

$$+ \frac{s^2 L}{2} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) - \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right] + \frac{s^2 L}{2} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right]$$

For 2nd last term:

$$\frac{s^2 L}{2} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) - \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right]$$

$$= \frac{s^2 L}{2N^2} \sum_{i=1}^N \mathbb{E} \left[\underbrace{\left\| \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) - \nabla f_i(\mathbf{x}_{i,k}) \right\|^2}_{\leq \sigma^2} \right]$$

(unbiasedness)

$$\leq \frac{s^2 L}{2N} \sigma^2$$

$$\mathbb{E} \left[\nabla f(\bar{\mathbf{x}}_k)^T \cdot \frac{1}{N} \sum_{i=1}^N \nabla f(\mathbf{x}_{i,k}) \right] \quad \left(\begin{array}{l} \text{iter. law of} \\ \mathbb{E}[\cdot] \end{array} \right)$$

$$\mathbb{E}[f(\bar{\mathbf{x}}_{k+1})] \leq \mathbb{E}[f(\bar{\mathbf{x}}_k)] - s \mathbb{E} \left[\nabla f(\bar{\mathbf{x}}_k)^T \frac{1}{N} \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) \right] + \frac{s^2 L \sigma^2}{2N}$$

$$+ \frac{s^2 L}{2} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right]$$

$$a^T b = \frac{1}{2} \|a\|^2 + \frac{1}{2} \|b\|^2 - \frac{1}{2} \|a-b\|^2$$

$$= \mathbb{E}[f(\bar{\mathbf{x}}_k)] - \frac{s-s^2 L}{2} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\mathbf{x}_{i,k}) \right\|^2 \right] - \frac{s}{2} \mathbb{E} \left[\left\| \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) - \nabla f(\bar{\mathbf{x}}_k) \right\|^2 \right]$$

$$+ \frac{s^2 L \sigma^2}{2N} + \frac{s}{2} \mathbb{E} \left[\left\| \left[\frac{1}{N} \sum_{i=1}^N \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}) \right] - \nabla f(\bar{\mathbf{x}}_k) \right\|^2 \right]$$

T₁

Now, we bound T_1

$$\begin{aligned} & \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \cancel{\nabla F_i(\bar{x}_k, \xi_{i,k})} - \nabla f(\bar{x}_k) \right\|^2 \right] \\ &= \frac{1}{N^2} \mathbb{E} \left[\left\| \sum_{i=1}^N (\nabla f(\bar{x}_k) - \cancel{\nabla F_i(\bar{x}_k, \xi_{i,k})}) \right\|^2 \right] \quad \left(\begin{array}{l} \mathbb{E} [\|z_1 + \dots + z_n\|^2] \quad (*) \\ \leq n \mathbb{E} [\|z_1\|^2 + \dots + \|z_n\|^2] \\ w/ n=N. \end{array} \right) \\ &\leq \frac{1}{N} \sum_{i=1}^N \mathbb{E} \left[\left\| \nabla f(\bar{x}_k) - \cancel{\nabla F_i(\bar{x}_k, \xi_{i,k})} \right\|^2 \right] \end{aligned}$$

$$\stackrel{*}{=} \frac{1}{N} \sum_{i=1}^N \mathbb{E} \left[\left\| \nabla f(\bar{x}_k) - \nabla f_i(\bar{x}_k) + \cancel{\nabla f_i(\bar{x}_k) - \nabla F_i(\bar{x}_k, \xi_{i,k})} \right\|^2 \right]$$

$$= \frac{1}{N} \sum_{i=1}^N \left[\underbrace{\mathbb{E} \left[\left\| \nabla f(\bar{x}_k) - \nabla f_i(\bar{x}_k) \right\|^2 \right]}_{\leq L^2 \|\bar{x}_k - x_{i,k}\|^2} + \underbrace{\mathbb{E} \left[\left\| \cancel{\nabla f_i(\bar{x}_k) - \nabla F_i(\bar{x}_k, \xi_{i,k})} \right\|^2 \right]}_{\leq \sigma^2} \right]$$

$$\leq \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} \left[\|\bar{x}_k - x_{i,k}\|^2 \right] + \cancel{\sigma^2}$$

agent - drift.

To bound the "agent - drift": $\mathbb{E} [\|\bar{x}_k - x_{i,k}\|^2] \triangleq Q_{i,k}$

$$Q_{i,k} = \mathbb{E} [\|\bar{x}_k - x_{i,k}\|^2] = \mathbb{E} \left[\left\| \frac{1}{N} \sum_{j=1}^N x_{j,k} - x_{i,k} e_i \right\|^2 \right]$$

$$\stackrel{\text{def}}{=} \mathbb{E} \left[\left\| \frac{1}{N} \left(\sum_{j=1}^N x_{j,k} \underbrace{W_{j,i}}_{=1} - s \partial F_j(x_{j,k}, \xi_{j,k}) \right) - \left(\sum_{j=1}^N x_{j,k} e_i - s \partial F_j(x_{j,k}, \xi_{j,k}) e_i \right) \right\|^2 \right]$$

$$= \mathbb{E} \left[\left\| \frac{1}{N} \left(\sum_{j=1}^N x_{j,k} - s \partial F_j(x_{j,k}, \xi_{j,k}) \right) - \left(\sum_{j=1}^N x_{j,k} e_i - s \partial F_j(x_{j,k}, \xi_{j,k}) e_i \right) \right\|^2 \right]$$

$$\stackrel{\text{recursion}}{=} \mathbb{E} \left[\left\| \frac{1}{N} \left(\cancel{x_{i,0}} - s \sum_{j=0}^{k-1} \partial F_j(x_{j,i}, \xi_{j,i}) \right) - \left(\cancel{x_{i,0}} e_i - s \sum_{j=0}^{k-1} \partial F_j(x_{j,i}, \xi_{j,i}) e_i \right) \right\|^2 \right]$$

$$= \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} s \partial F(\underline{x}_j, \xi_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$$

$$= s^2 \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} \partial F(\underline{x}_j, \xi_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$$

$\partial f(\underline{x}_j)$

$\left[\begin{array}{c} \vdots \\ \nabla f_1(\underline{x}_{1,j}) \dots \nabla f_n(\underline{x}_{n,j}) \\ \vdots \end{array} \right]$
 \downarrow
 $\text{dim } N$

$$\stackrel{+2-}{=} s^2 \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} \left(\partial F(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) + \partial f(\underline{x}_j) \right) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$$

$$\leq 2s^2 \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} \left(\partial F(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) \right) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$$

use (X)
 $w/n=2$

$$+ 2s^2 \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} \partial f(\underline{x}_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$$

T_2

T_3

Now, we bound T_2 :

$$T_2 = \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} \left(\partial F(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) \right) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$$

indep. $\sum_{j=0}^{k-1} \mathbb{E} \left[\left\| \left(\partial F(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) \right) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right) \right\|^2 \right]$

Cauchy-Schwarz $\leq \sum_{j=0}^{k-1} \mathbb{E} \left[\left\| \partial F(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) \right\|_2^2 \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{kj-1} \mathbf{e}_i \right\|^2 \right]$

l_2 -induced norm $\leq \|\cdot\|_F = \sum_{i=1}^N \|\nabla F_i(\underline{x}_j, \xi_j) - \nabla f_i(\underline{x}_j)\|^2 \leq N \sigma^2$

$A \in \mathbb{R}^{m \times n}$ (l_p -induced norm): $\|A\|_2 = \sqrt{\lambda_{\max}(A^T A)} = \sigma_{\max}(A)$.

$\|A\|_p = \sup_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_p}$

$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}|$ (max abs. col. sum).

$\|A\|_{\infty} = \max_{1 \leq i \leq m} \sum_{j=1}^n |a_{ij}|$ (max abs. row sum).

"entry-wise" $\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2} = \sqrt{\text{Tr}(A^T A)} = \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2(A)}$

$$\|A\|_2 = \sigma_{\max}(A) \leq \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2(A)} = \|A\|_F$$

(Continue to bound T_2).

$$T_2 \leq \sum_{j=1}^{k-1} \mathbb{E} \left[\underbrace{\|\partial f(\underline{x}_j, \underline{z}_j) - \partial f(\underline{x}_j)\|_F^2}_{\leq N\sigma^2} \underbrace{\|\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \mathbf{e}_i\|_2^2}_{\leq \beta^{2(k-j-1)}} \right]$$

$$\leq N\sigma^2 \underbrace{\sum_{j=0}^{k-1} \beta^{2(k-j-1)}}_{k \text{ terms}} \leq \frac{N\sigma^2}{1-\beta^2}$$

Now, we bound T_3 :

$$T_3 = \mathbb{E} \left[\left\| \sum_{j=0}^{k-1} \partial f(\underline{x}_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \mathbf{e}_i \right) \right\|^2 \right]$$

expand

$$= \sum_{j=0}^{k-1} \mathbb{E} \left[\underbrace{\left\| \partial f(\underline{x}_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \mathbf{e}_i \right) \right\|^2}_{T_4} \right]$$

$$+ \underbrace{\sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\left\langle \partial f(\underline{x}_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \mathbf{e}_i \right), \partial f(\underline{x}_{j'}) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} \mathbf{e}_i \right) \right\rangle \right]}_{T_5}$$

To bound T_3 , we need to further bound T_4 & T_5 .

$$T_4 = \sum_{j=0}^{k-1} \mathbb{E} \left[\left\| \partial f(\underline{x}_j) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \mathbf{e}_i \right) \right\|^2 \right]$$

Cauchy-Schwarz

$$\leq \sum_{j=0}^{k-1} \mathbb{E} \left[\underbrace{\left\| \partial f(\underline{x}_j) \right\|^2}_{\text{introduce a Lemma.}} \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \mathbf{e}_i \right\|^2 \right] \quad (\geq)$$

Lemma 1: $\mathbb{E}[\|\partial f(\underline{x}_{\cdot j})\|^2] \leq \sum_{h=1}^N \underbrace{3 \mathbb{E}[L^2 \|\underline{x}_{h,j} - \bar{x}_j\|^2]}_{Q_{j,h}} + 3NS^2 + 3\mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2]$

Proof: $\mathbb{E}[\|\partial f(\underline{x}_{\cdot j})\|^2] = \mathbb{E}[\|\underbrace{\partial f(\underline{x}_{\cdot j}) - \partial f(\bar{x}_j \mathbf{1}_N^T)}_{\left[\nabla f_1(\underline{x}_{1,j}) \dots \nabla f_N(\underline{x}_{N,j}) \right]_{d \times N}} + \partial f(\bar{x}_j \mathbf{1}_N^T) - \nabla f(\bar{x}_j) \mathbf{1}_N^T + \nabla f(\bar{x}_j) \mathbf{1}_N^T}\|^2]$

$\leq 3\mathbb{E}[\|\partial f(\underline{x}_{\cdot j}) - \partial f(\bar{x}_j \mathbf{1}_N^T)\|^2] + 3\mathbb{E}[\|\partial f(\bar{x}_j \mathbf{1}_N^T) - \nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2] + 3\mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2]$

$\leq 3\mathbb{E}[\|\partial f(\underline{x}_{\cdot j}) - \partial f(\bar{x}_j \mathbf{1}_N^T)\|_F^2] + 3\mathbb{E}[\|\partial f(\bar{x}_j \mathbf{1}_N^T) - \nabla f(\bar{x}_j) \mathbf{1}_N^T\|_F^2] + 3\mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2]$

$\left[\nabla f_1(\underline{x}_{1,j}) - \nabla f_1(\bar{x}_j), \dots, \nabla f_N(\underline{x}_{N,j}) - \nabla f_N(\bar{x}_j) \right]_{d \times N}$ $\left[\nabla f_1(\bar{x}_j) - \nabla f_1(\bar{x}_j), \dots, \nabla f_N(\bar{x}_j) - \nabla f_N(\bar{x}_j) \right]_{d \times N}$

$= 3\mathbb{E}\left[\sum_{h=1}^N \underbrace{\|\nabla f_h(\underline{x}_{h,j}) - \nabla f_h(\bar{x}_j)\|^2}_{\leq L^2 \|\underline{x}_{h,j} - \bar{x}_j\|^2}\right] + 3\mathbb{E}\left[\sum_{h=1}^N \underbrace{\|\nabla f_h(\bar{x}_j) - \nabla f_h(\bar{x}_j)\|^2}_{\leq S^2, \text{ non-i.i.d.}}\right] + 3\mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2]$

$\leq \sum_{h=1}^N 3\mathbb{E}[L^2 \|\underline{x}_{h,j} - \bar{x}_j\|^2] + 3NS^2 + 3\mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2]$ \square

(Continue on bounding T_4): Using Lemma 1 in (2):

$T_4 \leq \sum_{j=0}^{k-1} \sum_{h=1}^N 3\mathbb{E}[L^2 \|\underline{x}_{h,j} - \bar{x}_j\|^2] + 3NS^2 + 3\mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2] \times$

$\left\| \frac{1}{N} \mathbf{1}_N - \mathbf{W}^{k,j} + \mathbf{e}_i \right\|^2$
 $\leq \beta^{2(k-j-1)}$

$$\leq \frac{3N\beta^2}{1-\beta^2} + \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[\underbrace{L^2 \|x_{h,j} - \bar{x}_j\|^2}_{Q_{h,j}} \right] \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} e_i \right\|^2$$

$$+ \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[\left\| \nabla f(\bar{x}_j) \mathbf{1}_N^T \right\|^2 \right] \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} e_i \right\|^2 \quad (3)$$

Now, we bound T_5 :

$$T_5 = \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\left\langle \nabla f(x_{\cdot,j}) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j} e_i \right), \nabla f(x_{\cdot,j'}) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} e_i \right) \right\rangle \right]$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\left\| \nabla f(x_{\cdot,j}) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j} e_i \right) \right\| \cdot \left\| \nabla f(x_{\cdot,j'}) \left(\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} e_i \right) \right\| \right]$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\left\| \nabla f(x_{\cdot,j}) \right\| \cdot \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j} e_i \right\| \cdot \left\| \nabla f(x_{\cdot,j'}) \right\| \cdot \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} e_i \right\| \right]$$

$$\stackrel{\text{Young's}}{\leq} \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\frac{1}{2} \left\| \nabla f(x_{\cdot,j}) \right\|^2 \cdot \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j} e_i \right\|^2 + \frac{1}{2} \left\| \nabla f(x_{\cdot,j'}) \right\|^2 \cdot \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} e_i \right\|^2 \right]$$

$\leftarrow \leq \beta^{k-j-1}$ $\leftarrow \leq \beta^{k-j'-1}$

$$+ \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\frac{1}{2} \left\| \nabla f(x_{\cdot,j}) \right\|^2 \cdot \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j} e_i \right\|^2 + \frac{1}{2} \left\| \nabla f(x_{\cdot,j'}) \right\|^2 \cdot \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} e_i \right\|^2 \right]$$

$$\leq \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\left(\frac{1}{2} \left\| \nabla f(x_{\cdot,j}) \right\|^2 + \frac{1}{2} \left\| \nabla f(x_{\cdot,j'}) \right\|^2 \right) \beta^{2(k - \frac{j+j'}{2} - 1)} \right]$$

k^2 terms

$$= \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[\underbrace{\left\| \nabla f(x_{\cdot,j}) \right\|^2}_{\text{Lemma 1}} \beta^{2(k - \frac{j+j'}{2} - 1)} \right]$$

$$\begin{aligned}
&\leq \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \left[\sum_{h=1}^N \mathbb{E} \left[L^2 \underbrace{\|x_{hj} - \bar{x}_j\|^2}_{Q_{hj}} \right] + 3NS^2 + 3 \mathbb{E} \left[\|\nabla f(\bar{x}_j) \mathbb{1}_N\|^2 \right] \right] \times \\
&\quad \beta^{2(k - \frac{j+j'}{2} - 1)} \quad \times \beta^{2(k - \frac{j+j'}{2} - 1)} \\
&= \underbrace{\sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} 3NS^2 \beta^{2(k - \frac{j+j'}{2} - 1)}}_{T_6} + \underbrace{3 \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \left[\sum_{h=1}^N \mathbb{E} [L^2 Q_{hj}] + \mathbb{E} [\|\nabla f(\bar{x}_j) \mathbb{1}_N\|^2] \right]}_{T_7}
\end{aligned}$$

Note T_6 can be ded as:

$$\begin{aligned}
T_6 &= \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} 3NS^2 \beta^{2(k - \frac{j+j'}{2} - 1)} = 6NS^2 \sum_{j=0}^{k-1} \sum_{j'>j}^{k-1} \beta^{2(k - \frac{j+j'}{2} - 1)} \\
&= 6NS^2 \sum_{j=0}^{k-1} \beta^{k-j-1} \sum_{j'>j}^{k-1} \beta^{k-j'-1} = 6NS^2 \sum_{j=0}^{k-1} \beta^{k-j-1} [1 + \beta + \dots + \beta^{k-j-2}] \\
&= 6NS^2 \sum_{j=0}^{k-1} \beta^{k-j-1} \frac{1 - \beta^{k-j-1}}{1 - \beta} = \frac{6NS^2}{1 - \beta} \left[\underbrace{\sum_{j=0}^{k-1} \beta^{k-j-1}}_{k \text{ terms}} - \underbrace{\sum_{j=0}^{k-1} \beta^{2(k-j-1)}}_{k \text{ terms}} \right] \\
&= \frac{6NS^2}{1 - \beta} \left[\frac{1 - \beta^k}{1 - \beta} - \frac{1 - \beta^{2k}}{1 - \beta^2} \right] = 6NS^2 \frac{(1 - \beta^k) (\beta - \beta^k)}{(1 - \beta)^2 (1 + \beta)} \leq \frac{6NS^2}{(1 - \beta)^2}
\end{aligned}$$

Now, we bound T_7 .

$$\begin{aligned}
T_7 &= 3 \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \left[\sum_{h=1}^N \mathbb{E} [L^2 Q_{hj}] + \mathbb{E} [\|\nabla f(\bar{x}_j) \mathbb{1}_N\|^2] \right] \beta^{2(k - \frac{j+j'}{2} - 1)} \\
&= 6 \sum_{j=0}^{k-1} \left[\sum_{h=1}^N \mathbb{E} [L^2 Q_{hj}] + \mathbb{E} [\|\nabla f(\bar{x}_j) \mathbb{1}_N\|^2] \right] \underbrace{\sum_{j'=j+1}^{k-1} \beta^{2(k - \frac{j+j'}{2} - 1)}}_{k-j-1 \text{ terms}}
\end{aligned}$$

$$\leq 6 \sum_{j=0}^{k-1} \left[\sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] + \mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2] \right] \frac{\rho^{k-j-1}}{1-\beta}$$

Plug T_6, T_7 into T_5 , and then plugging T_5 & T_4 into T_3 yields:

$$T_3 \leq 3 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] \|\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i\|^2$$

$$+ 3 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2] \|\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i\|^2$$

$$+ 6 \sum_{j=0}^{k-1} \left[\sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] + \mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2] \right] \frac{\rho^{k-j-1}}{1-\beta}$$

$$+ \underbrace{\frac{3N\beta^2}{(1-\beta^2)} + \frac{6N\beta^2}{(1-\beta)^2}}_{(1-\beta)(1+\beta) \geq (1-\beta)^2} \leq \frac{9N\beta^2}{(1-\beta)^2}$$

Putting the bounds for T_2 & T_3 back to $Q_{i,k}$:

$$Q_{i,k} \leq \underbrace{\frac{2s^2 N \sigma^2}{1-\beta^2}}_{2s^2 T_2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] \underbrace{\|\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i\|^2}_{\leq \beta^{2(k-j-1)}}$$

$$+ 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N^T\|^2] \|\frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i\|^2$$

$$+ 12s^2 \sum_{j=0}^{k-1} \left[\sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] + \mathbb{E}[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2] \right] \frac{\rho^{k-j-1}}{1-\beta} + \frac{18s^2 N \beta^2}{(1-\beta)^2}$$

$$\leq \frac{2s^2 N \sigma^2}{1-\beta^2} + \frac{18s^2 N \beta^2}{(1-\beta)^2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] \beta^{2(k-j-1)}$$

$$+ 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[\left\| \nabla f(\bar{x}_j) \underline{1}_N \right\|^2 \right] \beta^{2(k-j-1)}$$

$$+ 12s^2 \sum_{j=0}^{k-1} \left[\sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] + \mathbb{E} \left[\left\| \nabla f(\bar{x}_j) \underline{1}_N \right\|^2 \right] \right] \frac{\beta^{k-j-1}}{1-\beta}$$

$$= \frac{2s^2 N \sigma^2}{1-\beta^2} + \frac{18s^2 N \beta^2}{(1-\beta)^2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] \left(\beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta} \right)$$

$$+ 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[\left\| \nabla f(\bar{x}_j) \underline{1}_N \right\|^2 \right] \left(\beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta} \right)$$

$$\text{Thus: } T_1 \leq \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} \left[\left\| \bar{x}_k - x_{i,k} \right\|^2 \right] = \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} [Q_{i,k}]$$

Recall:

$$\mathbb{E} [f(\bar{x}_k)] \leq \mathbb{E} [f(\bar{x}_k)] - \frac{s-s^2L}{2} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(x_{i,k}) \right\|^2 \right]$$

$$- \frac{s}{2} \mathbb{E} \left[\left\| \nabla f(\bar{x}_k) \right\|^2 \right] + \frac{s^2 L \sigma^2}{2N} + \frac{s}{2} \mathbb{E} [T_1] \quad (4)$$

Summing $k=0, \dots, k-1$ yields:

$$\frac{s-s^2L}{2} \sum_{k=0}^{k-1} \mathbb{E} \left[\left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(x_{i,k}) \right\|^2 \right] + \frac{s}{2} \sum_{k=0}^{k-1} \mathbb{E} \left[\left\| \nabla f(\bar{x}_k) \right\|^2 \right]$$

$$\leq f(0) - f^* + \sum_{k=0}^{k-1} \frac{s^2 L \sigma^2}{2N} + \frac{s}{2} \sum_{k=0}^{k-1} \mathbb{E} [T_1]$$

$$\leq \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} [Q_{i,k}] = L^2 \mathbb{E} [M_k]$$

$$M_k \stackrel{\text{def}}{=} \frac{1}{N} \sum_{i=1}^N Q_{i,k}$$

Now, need to find $\mathbb{E}[M_k]$:

$$\mathbb{E}[M_k] = \frac{1}{N} \mathbb{E}\left[\sum_{i=1}^N Q_{i,k}\right]$$

$$\leq \frac{2s^2 N \sigma^2}{1-\beta^2} + \frac{(8s^2 N)^2}{(1-\beta)^2} + 6s^2 \sum_{j=0}^{k-1} \sum_{i=1}^N \mathbb{E}\left[\left\|\nabla f(\bar{x}_j) \frac{\mathbf{1}_N}{N}\right\|^2\right] \times$$

$$\left(\beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta}\right)$$

$$+ 6s^2 N L \sum_{j=0}^{k-1} \mathbb{E}[M_j] \left(\beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta}\right)$$

Summing the above from $k=0$ to $k-1$, and rearranging:

$$\sum_{k=0}^{K-1} \mathbb{E}[M_k] \leq \frac{2s^2 N \sigma^2}{(1-\beta^2) \underbrace{\left(1 - \frac{(8s^2 N)^2}{(1-\beta)^2}\right)}_{D_2}} K + \frac{(8s^2 N)^2}{(1-\beta)^2 \underbrace{\left(1 - \frac{(8s^2 N)^2}{(1-\beta)^2}\right)}_{D_2}} K$$

$$+ \frac{(8s^2 N)}{(1-\beta)^2 \underbrace{\left(1 - \frac{(8s^2 N)^2}{(1-\beta)^2}\right)}_{D_2}} \sum_{k=0}^{K-1} \mathbb{E}\left[\left\|\nabla f(\bar{x}_k)\right\|^2\right] \quad (5)$$

Plugging (5) into (4), we have:

$$\frac{s-s^2 L}{2} \sum_{k=0}^{K-1} \mathbb{E}\left[\left\|\frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k})\right\|^2\right] + \frac{s}{2} \sum_{k=1}^{K-1} \mathbb{E}\left[\left\|\nabla f(\bar{x}_k)\right\|^2\right]$$

$$\leq f(0) - f^* + \frac{s^2 k L \sigma^2}{2N} + \frac{s^3 L^2 N \sigma^2}{(1-\beta^2) D_2} + \frac{9 N s^3 L^2}{(1-\beta)^2 D_2}$$

$$+ \frac{9 N s^3 L^2}{(1-\beta)^2 D_2} \sum_{k=0}^{K-1} \mathbb{E}\left[\left\|\nabla f(\bar{x}_k)\right\|^2\right]$$

and defining $D_1 = \frac{1}{2} - \frac{9s^3 L^2 N}{(1-\beta)^2 D_2}$

Rearranging & dividing both sides by sK , arrives at stated result. \square

$$\left(\frac{1}{2}, \frac{2}{3}\right)$$

Proof of Corollary 2: If $s = \frac{1}{2L + \sigma\sqrt{KN}} < \frac{1}{2}$, then $\frac{1-sL}{2} > 0$

Dropping the term associated w/ $\left\| \frac{1}{N} \sum_{i=1}^N \nabla f(x_{i,k}) \right\|^2$, we have:

$$\begin{aligned} \frac{D_1}{K} \sum_{k=0}^{K-1} \mathbb{E} [\| \nabla f(x_k) \|^2] &\leq \frac{2(f(0) - f^*)L}{k} + \frac{(f(0) - f^*)\sigma}{\sqrt{KN}} + \frac{L\sigma^2}{4NL + 2\sigma\sqrt{KN}} \\ &+ \frac{L^2N}{(2L + \sigma\sqrt{KN})^2 D_2} \left(\frac{\sigma^2}{1 - \beta^2} + \frac{9s^2}{(1 - \beta)^2} \right) \\ &\leq \frac{2(f(0) - f^*)L}{k} + \frac{(f(0) - f^* + 4/2)\sigma}{\sqrt{KN}} + \frac{L^2N}{(\sigma\sqrt{KN})^2 D_2} \left(\frac{\sigma^2}{1 - \beta^2} + \frac{9s^2}{(1 - \beta)^2} \right) \end{aligned} \quad (b)$$

Recall $D_1 = \frac{1}{2} - \frac{9s^2L^2N}{(1 - \beta)^2 D_2}$, $D_2 = 1 - \frac{18s^2}{(1 - \beta)^2} NL^2$

$$\left. \begin{aligned} \text{If } s^2 \leq \frac{(1 - \beta)^2}{36NL^2} &\Rightarrow D_2 \geq \frac{1}{2} \quad s^2 \leq \frac{(1 - \beta)^2}{72L^2N} \Rightarrow D_1 \geq \frac{1}{4} \\ \text{Since } s = \frac{1}{2L + \sigma\sqrt{KN}} \leq \frac{1}{\sigma\sqrt{KN}} &\Rightarrow s^2 \leq \frac{N}{\sigma^2 K} \end{aligned} \right\} \Rightarrow$$

If $\frac{N}{\sigma^2 K} \leq \min \left\{ \frac{(1 - \beta)^2}{36NL^2}, \frac{(1 - \beta)^2}{72NL^2} \right\}$, then $D_2 \geq \frac{1}{2}$, $D_1 \geq \frac{1}{4}$.

Now, replacing D_1 & D_2 by $\frac{1}{4}$ & $\frac{1}{2}$, resp., in (b):

$$\begin{aligned} \frac{1}{4K} \sum_{k=0}^{K-1} \mathbb{E} [\| \nabla f(x_k) \|^2] &\leq \frac{2(f(0) - f^*)L}{k} + \frac{(f(0) - f^* + 4/2)\sigma}{\sqrt{KN}} \\ &+ \frac{2L^2N}{(\sigma\sqrt{KN})^2} \left(\frac{\sigma^2}{1 - \beta^2} + \frac{9s^2}{(1 - \beta)^2} \right) \\ &\leq \frac{(4f(0) - 4f^* + 2L)\sigma}{\sqrt{KN}} \quad \text{if (A) is true} \end{aligned}$$

Combine these two yields the stated result.



Proof of Thm 3: With $s = \frac{1}{2L + \sigma\sqrt{K/N}}$, we have from (5):

$$\frac{1}{K} \sum_{k=0}^{K-1} \underbrace{\mathbb{E}[M_k]}_{\substack{\text{avg agent} \\ \text{drift}}} \leq \frac{2s^2 N \sigma^2}{(1-\beta^2) D_2} + \frac{18s^2 N \rho^2}{(1-\beta)^2 D_2} + \frac{18s^2 N}{(1-\beta)^2 D_2 K} \sum_{k=0}^{K-1} \mathbb{E} \left[\|\nabla f(\bar{x}_k)\|^2 \right] \quad (5)$$

Corollary

$$\leq \frac{2s^2 N \sigma^2}{(1-\beta^2) D_2} + \frac{18s^2 N \rho^2}{(1-\beta)^2 D_2} + \frac{\rho^2 L N}{D_1 D_2} \left(\frac{\sigma^2}{1-\beta^2} + \frac{9s^2}{(1-\beta)^2} \right) + \frac{18s^2 N}{(1-\beta)^2 D_2} \left(\frac{f(x^*) - s^2 \sigma^2}{sK} + \frac{s^2 \sigma^2}{2N\rho} \right)$$

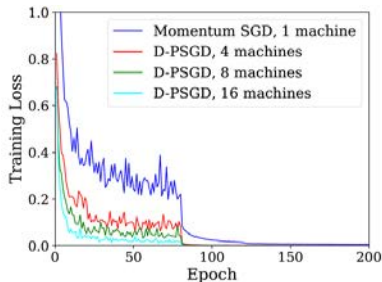
$$\triangleq Ns^2 \frac{A}{D_2}$$



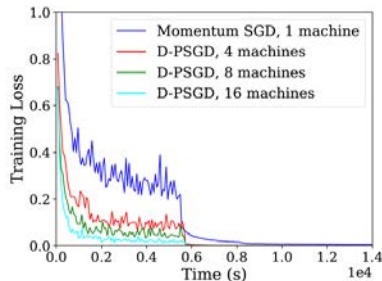
Numerical Results of DSGD

- Linear Speedup Effect

- ▶ 32-layer residual network and CIFAR-10 dataset
- ▶ Up to 16 machines; each machine includes two Xeon E5-2680 8-core processors and a NVIDIA K20 GPU



(a) Iteration vs Training Loss



(b) Time vs Training Loss

A “Tug of War” in DSGD

Revisit the DSGD algorithm:

- The algorithmic update at each agent is:

$$\mathbf{x}_{i,k+1} = \underbrace{\sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k}}_{\text{Avg consensus step}} - \underbrace{s_k \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k})}_{\text{Local SGD step}},$$

where $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$.

The average consensus step and the local SGD step “conflict” with each other.
Can we do better?

The Gradient Tracking Idea

[Lorenzo-Scutari, TSIPN'16]
"full grad".

Gradient-Tracking DSGD: [Lu et al., DSW'19]:

- 1 Initialization: Let $k = 1$. Choose initial values for $\mathbf{x}_{i,1}$ and step-size s_1 . Define an **auxiliary variable** $\mathbf{y}_{i,k}$ with $\mathbf{y}_{i,1} = \nabla F_i(\mathbf{x}_{i,1}, \xi_{i,1})$.
- 2 In k -th iteration: Each node sends its local copy ^{and $\mathbf{y}_{i,k}$} to its neighbors.
- 3 Upon reception of all local copies from its neighbors, each node updates its local copy:

$$\mathbf{x}_{i,k+1} = \sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k} - s_k \mathbf{y}_{i,k},$$

$$\mathbf{y}_{i,k+1} = \sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{y}_{j,k} + \nabla F_i(\mathbf{x}_{i,k+1}, \xi_{i,k+1}) - \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}).$$

where $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$.

- 4 Let $k \leftarrow k + 1$ and go to Step 2

Notation:

$$\underline{X}_k = \begin{bmatrix} x_{1,k} & \dots & x_{N,k} \\ \vdots & & \vdots \end{bmatrix}_{d \times N}, \quad \underline{Y}_k = \begin{bmatrix} y_{1,k} & \dots & y_{N,k} \\ \vdots & & \vdots \end{bmatrix}_{d \times N}$$

$$\partial \underline{F}(\underline{X}_k, \underline{\xi}_k) = \left[\partial F_1(x_{1,k}, \xi_{1,k}) \dots \partial F_N(x_{N,k}, \xi_{N,k}) \right]_{d \times N}$$

$$\bar{x}_k = \frac{1}{N} \sum_{i=1}^N x_{i,k}, \quad \bar{y}_k = \frac{1}{N} \sum_{i=1}^N y_{i,k}$$

In matrix form:

$$\begin{cases} \underline{X}_{k+1} = \underline{X}_k \underline{W} - s_k \underline{Y}_k \\ \underline{Y}_{k+1} = \underline{Y}_k \underline{W} + \partial \underline{F}(\underline{X}_{k+1}, \underline{\xi}_{k+1}) - \partial \underline{F}(\underline{X}_k, \underline{\xi}_k) \end{cases}$$

Right multiply both eqns by $\frac{1}{N} \mathbf{1}_N$:

$$\Rightarrow \begin{cases} \frac{1}{N} \underline{X}_{k+1} \mathbf{1}_N = \frac{1}{N} \underline{X}_k \underbrace{\underline{W} \mathbf{1}_N}_{=\mathbf{1}_N} - \frac{s_k}{N} \underline{Y}_k \mathbf{1}_N \\ \frac{1}{N} \underline{Y}_{k+1} \mathbf{1}_N = \frac{1}{N} \underline{Y}_k \underbrace{\underline{W} \mathbf{1}_N}_{=\mathbf{1}_N} + \frac{1}{N} \partial \underline{F}(\underline{X}_{k+1}, \underline{\xi}_{k+1}) \mathbf{1}_N - \frac{1}{N} \partial \underline{F}(\underline{X}_k, \underline{\xi}_k) \mathbf{1}_N \end{cases}$$

$$\Rightarrow \begin{cases} \bar{x}_{k+1} = \bar{x}_k - s_k \bar{y}_k & (1) \\ \bar{y}_{k+1} = \bar{y}_k + \frac{1}{N} \sum_{i=1}^N \partial F_i(\underline{X}_{k+1}, \underline{\xi}_{k+1}) - \frac{1}{N} \sum_{i=1}^N \partial F_i(\underline{X}_k, \underline{\xi}_k) & (2) \end{cases}$$

From (2), by recursion on \bar{y}_k :

$$\bar{y}_{k+1} = \frac{1}{N} \sum_{i=1}^N \partial F_i(\underline{X}_{k+1}, \underline{\xi}_{k+1}) \quad \text{From (1):}$$

$$\bar{x}_{k+1} = \bar{x}_k - \frac{s_k}{N} \sum_{i=1}^N \partial F_i(x_{i,k}, \xi_{i,k})$$

Exactly the same as DSGD.

Convergence Results for GT-DSGD

$$\underline{A} \in \mathbb{R}^{m \times n}, \quad \underline{B} \in \mathbb{R}^{p \times q}$$

$$\underline{A} \otimes \underline{B} = \begin{bmatrix} a_{11} \underline{B} & \dots & a_{1n} \underline{B} \\ \vdots & & \vdots \\ a_{m1} \underline{B} & \dots & a_{mn} \underline{B} \end{bmatrix} \in \mathbb{R}^{mp \times nq}$$

- Define $P^k \triangleq \mathbb{E}[f(\bar{\mathbf{x}}_k)] + \mathbb{E}[\|\mathbf{x}_k - \mathbf{1}_N \otimes \bar{\mathbf{x}}_k\|^2] + Q \mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|^2]$

Theorem 4 (Convergence of Agent-Average [Lu et al. DSW'19])

If the step-size is set to $\frac{C_0}{\sqrt{T}}$, then it holds that:

$$C_1 \mathbb{E}[\|\bar{\mathbf{y}}_k\|^2] + \frac{C_2}{C_0} \mathbb{E}[\|\mathbf{x}_t - \mathbf{1}_N \otimes \bar{\mathbf{x}}_t\|^2] \leq \left(\frac{P^0 - P^*}{C_0} + C_4 C_0 \sigma^2 \right) \frac{1}{\sqrt{T}}$$

Kronecker product

$$\begin{bmatrix} \mathbf{x}_{1,t} \\ \vdots \\ \mathbf{x}_{N,t} \end{bmatrix} \quad \begin{bmatrix} \bar{\mathbf{x}}_t \\ \vdots \\ \bar{\mathbf{x}}_t \end{bmatrix}$$

[Zhang, Liu, Zhu, Bentley, Infocom'20]

$$O\left(\frac{1}{\sqrt{T}}\right)$$

[Mobili, Avc'20]

[Liu, Zhang, Liu, Lu, NeurIPS'21] "MARL" "single-loop" $O\left(\frac{1}{\sqrt{T}}\right)$

Convergence Results for GT-GSGD

Theorem 5 (Contraction of Consensus Gap [Lu et al. DSW'19])

Let ρ be some constant such that $(1 + \rho)\beta^2 < 1$. It holds that:

$$\begin{aligned}\mathbb{E}[\|\mathbf{x}_{k+1} - \mathbf{1}_N \otimes \bar{\mathbf{x}}_{k+1}\|] &\leq (1 + \rho)\beta^2 \mathbb{E}[\|\mathbf{x}_k - \mathbf{1}_N \otimes \bar{\mathbf{x}}_k\|^2] \\ &\quad + 3 \left(1 + \frac{1}{\rho}\right) s^2 \mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|^2] + 6 \left(1 + \frac{1}{\rho}\right) s^2 \kappa \sigma^2, \\ \mathbb{E}[\|\mathbf{y}_{k+1} - \mathbf{1}_N \otimes \bar{\mathbf{y}}_{k+1}\|] &\leq \frac{4L^2 s^2}{N} \left(1 + \frac{1}{\beta}\right)^2 \|\bar{\mathbf{y}}_k\|^2 \\ &\quad + \left(\frac{L^2}{N^2} \beta^2 (1 + \rho) \left(1 + \frac{1}{\rho}\right) + \frac{4L^2}{N^2} \left(1 + \frac{1}{\rho}\right)^2\right) \mathbb{E}[\|\mathbf{x}_k - \mathbf{1}_N \otimes \bar{\mathbf{x}}_k\|^2] \\ &\quad + \left((1 + \rho)\beta^2 + \frac{4L^2 s^2}{N^2} \left(1 + \frac{1}{\rho}\right)^2\right) \mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|^2] \\ &\quad + \frac{4L^2 s^2}{N^2} \left(1 + \frac{1}{\rho}\right)^2 \kappa \sigma^2.\end{aligned}$$

Next Class

Zeroth-Order Methods