

Lecture 2-1. Math Background Review.

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1. Basic Analysis:

A. i.° Norm: A fn $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is called norm if:

* (non-neg.): $f(x) \geq 0$, $\forall x \in \mathbb{R}^n$, $f(x) = 0$ iff $x = 0$.

* (homogeneity): $f(tx) = |t|f(x)$, $\forall x \in \mathbb{R}^n$, $t \in \mathbb{R}$.

* (triangle inequality): $f(x+y) \leq f(x) + f(y)$, $\forall x, y \in \mathbb{R}^n$.

If $f(x)$ is a norm, we denote it as $\|x\|$.

2° Norm $\|x\|$'s meaning:

* $\|x\|$: length of x

* $\|x-y\|$: dist. btwn x and y .

3° Unit Ball: set of vectors with $\|x\| \leq 1$.

$$\mathbb{B} = \{x \in \mathbb{R}^n; \|x\| \leq 1\}.$$

Ex: * l_2 -norm (Euclidean norm): $\|x\|_2 \triangleq (x^T x)^{\frac{1}{2}} = (x_1^2 + \dots + x_n^2)^{\frac{1}{2}}$.

* l_1 -norm (sum-abs-val): $\|x\|_1 \triangleq |x_1| + |x_2| + \dots + |x_n|$.

* l_∞ -norm (Chebyshev): $\|x\|_\infty \triangleq \max\{|x_1|, \dots, |x_n|\}$.

* l_p -norm ($p \geq 1$): $\|x\|_p \triangleq (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}}$

$$\|x\|_\infty = \lim_{p \rightarrow \infty} \|x\|_p$$

Proof: $\|x\|_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}} = \left(\frac{|x_1|^p}{\|x\|_\infty^p} + \dots + \frac{|x_n|^p}{\|x\|_\infty^p} \right)^{\frac{1}{p}} \|x\|_\infty$
 $\leq (1 + \dots + 1)^{\frac{1}{p}} \|x\|_\infty = n^{\frac{1}{p}} \|x\|_\infty \rightarrow \|x\|_\infty$ as $p \rightarrow \infty$.

Let $i^* \in \operatorname{argmax}\{|x_i|, \forall i\}$.

$$\|x\|_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}} \geq (|x_{i^*}|^p)^{\frac{1}{p}} = |x_{i^*}| = \|x\|_\infty.$$

Note $n^{\frac{1}{p}} \rightarrow 1$ as $p \rightarrow \infty$.



4° Equivalence of Norms:

Suppose $\|\cdot\|_a$ and $\|\cdot\|_b$ are norms of \mathbb{R}^n . Then $\exists \alpha, \beta > 0$
s.t. $\forall \underline{x} \in \mathbb{R}^n$, $\alpha \|\underline{x}\|_a \leq \|\underline{x}\|_b \leq \beta \|\underline{x}\|_a$.

$$\text{Ex: } \|\underline{x}\|_2 \leq \|\underline{x}\|_1 \leq \sqrt{n} \|\underline{x}\|_2.$$

$$\|\underline{x}\|_\infty \leq \|\underline{x}\|_2 \leq \sqrt{n} \|\underline{x}\|_\infty$$

$$\|\underline{x}\|_\infty \leq \|\underline{x}\|_1 \leq n \|\underline{x}\|_\infty.$$

2. Convergent Sequences and Limits:

1° Def (Convergence): A seq. of vectors $\underline{x}_1, \dots, \underline{x}_n, \dots$ are said to be convergent to a limit pt. $\bar{\underline{x}}$ if $\forall \varepsilon > 0$, $\exists N_\varepsilon \in \mathbb{N}$

s.t. $\|\underline{x}_k - \bar{\underline{x}}\| < \varepsilon$, $\forall k \geq N_\varepsilon$. ($\{\underline{x}_k\} \rightarrow \bar{\underline{x}}$ as $k \rightarrow \infty$, $\lim_{k \rightarrow \infty} \underline{x}_k = \bar{\underline{x}}$).

2° Def (Cauchy Seq.): A seq. $\{\underline{x}_k\}$ is Cauchy if

$\forall \varepsilon > 0$, $\exists N \in \mathbb{N}$ s.t. $\|\underline{x}_m - \underline{x}_n\| < \varepsilon$, $\forall m, n \geq N$.

Thm: A seq. in \mathbb{R}^n has a limit iff it's Cauchy.

Ex: (p-series). $a_n = \frac{1}{n^p}$. Show $\{b_n\} \cong \left\{ \sum_{k=1}^n a_k \right\}$ has a limit

for $p=2$, but doesn't converge for $p=1$.

Proof: w.l.o.g., let $m, n \in \mathbb{N}$ and $m < n$.

$$\text{For } p=2, \quad b_n - b_m = \sum_{k=1}^n \frac{1}{k^2} - \sum_{k=1}^m \frac{1}{k^2} = \sum_{k=m+1}^n \frac{1}{k^2} \leq \sum_{k=m+1}^n \frac{1}{k} \cdot \frac{1}{k-1}$$

$$= \sum_{k=m+1}^n \left(\frac{1}{k-1} - \frac{1}{k} \right) = \frac{1}{m} - \frac{1}{m+1} + \frac{1}{m+1} - \frac{1}{m+2} + \dots + \frac{1}{n-1} - \frac{1}{n}$$

$$= \frac{1}{m} - \frac{1}{n} < \frac{1}{m} < \varepsilon, \text{ if } m \text{ is suff. large.}$$

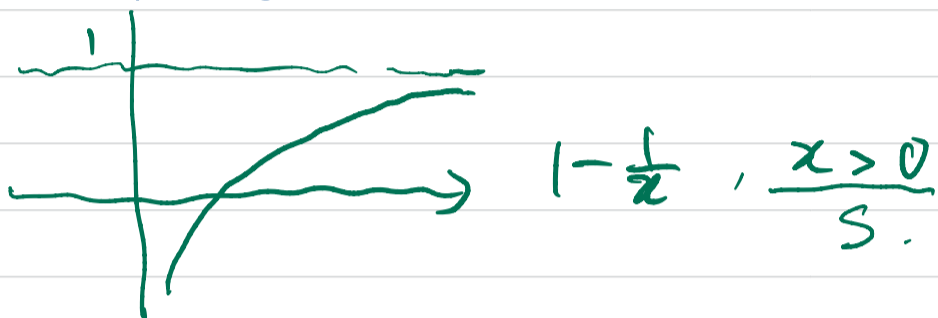
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$$\text{For } p=1, \quad b_n - b_m = \sum_{k=1}^n \frac{1}{k} - \sum_{k=1}^m \frac{1}{k} = \sum_{k=m+1}^n \frac{1}{k} = \frac{1}{m+1} + \dots + \frac{1}{n}$$

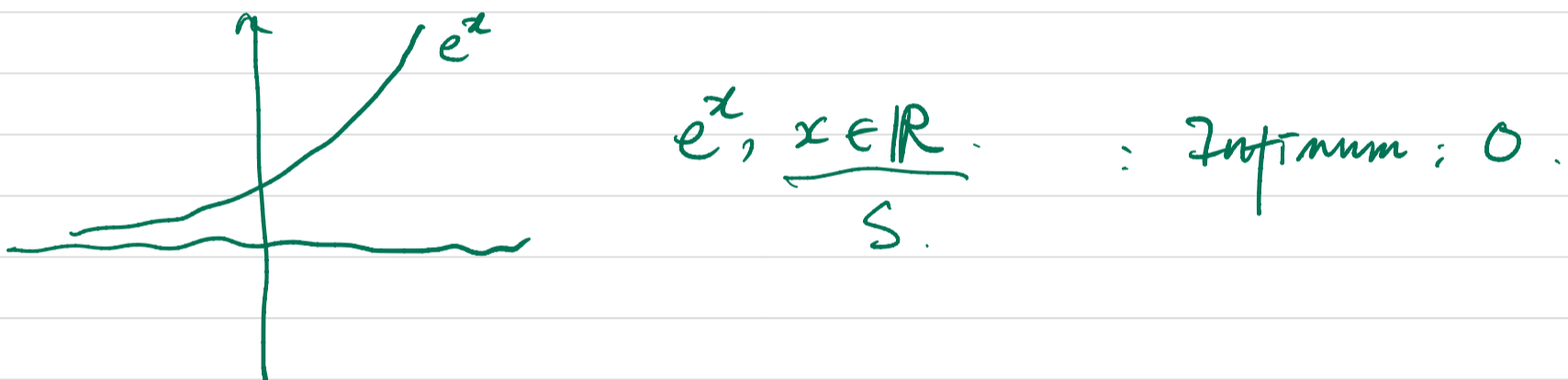
$$\geq \frac{n-m}{n} = 1 - \frac{m}{n}.$$

Consider any $\varepsilon > 0$, no matter how large m is, can choose $n \geq \lceil \frac{m}{1-\varepsilon} \rceil$, so that $b_n - b_m \geq \varepsilon$. □

3° Supremum of S (least UB): Smallest possible α satisfying $\alpha \geq x, \forall x \in S$.



4° Infimum of S (largest LB): Largest $\alpha \leq x, \forall x \in S$.



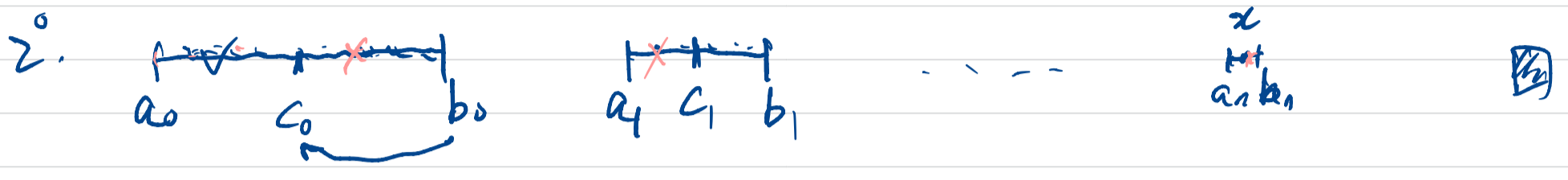
Thm: (Bolzano-Weierstrass): Every bnded seq. in \mathbb{R}^n has a convergent subseq.

Proof: 1. Every inf. seq. $\{x_n\}$ in \mathbb{R}^1 has mono. subseq.



2. MCT: if $\{a_n\}$ is mono seq. reals, then $\{a_n\}$ has a limit iff $\{a_n\}$ is bnded.

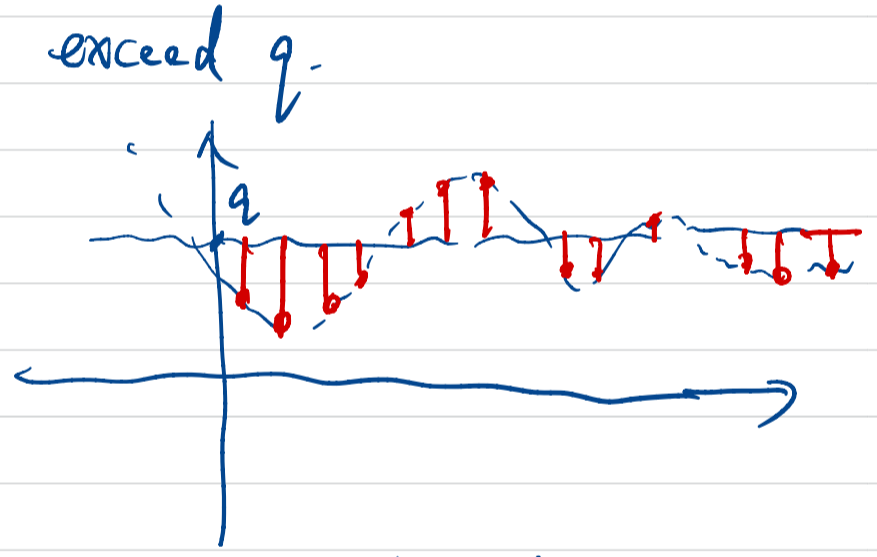
3. \mathbb{R}^n : Extract subseq. each dim. sequentially. □



3° Maximum, Minimum. (achievable).

4° limsup, limit:

* The limit supremum $\limsup_{k \rightarrow \infty} x_k$ is infimum of all $q \in \mathbb{R}$ for which all but a finite # of elements in $\{x_k\}$ exceed q .



$$\limsup_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \left\{ \sup_{m \geq n} x_m \right\} \underbrace{\hspace{10em}}_{a_n}$$

* limit infimum - $\liminf_{k \rightarrow \infty} x_k$ - supremum - $\lim_{n \rightarrow \infty} \left\{ \inf_{m \geq n} x_m \right\}$

* limsup and limit always exist.

$$\{x_n\} \text{ converge iff } \limsup_{n \rightarrow \infty} x_n = \liminf_{n \rightarrow \infty} x_n$$

3. Functions:

(5)

1° Cont. fn: A fn $f: S \rightarrow \mathbb{R}$ is cont. at $\bar{x} \in S$ if $\forall \epsilon > 0$, $\exists \delta > 0$, s.t. $x \in S$ with $\|x - \bar{x}\| < \delta \rightarrow |f(x) - f(\bar{x})| < \epsilon$.

write: $f(x) \rightarrow f(\bar{x})$, as $x \rightarrow \bar{x}$.

Fact: Cont. fn achieves both maximum & minimum over a non-empty compact set. closed & bnded.

2° Diff'ble fn:



(1) S non-empty set in \mathbb{R}^n , $\bar{x} \in \text{int } S$, and $f: S \rightarrow \mathbb{R}$.

f is diff'ble at \bar{x} if \exists a vector (called gradient).

$$\nabla f(\bar{x}) \triangleq \left[\frac{\partial f(\bar{x})}{\partial x_1}, \dots, \frac{\partial f(\bar{x})}{\partial x_n} \right]^T \text{ at } \bar{x} \text{ and fn } \beta(x, \bar{x}) \rightarrow 0.$$

as $x \rightarrow \bar{x}$, such that:

$$f(x) = \underbrace{f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x})}_{\text{FO - approx.}} + \underbrace{\|x - \bar{x}\| \beta(x, \bar{x})}_{o(\|x - \bar{x}\|)}, \quad \forall x \in S$$

(2) f is called twice diff'ble at \bar{x} if, in addition to grad, \exists symmetric matrix $\underline{H}(\bar{x})$ (called Hessian matrix) of f at \bar{x} , and $\beta(x, \bar{x}) \rightarrow 0$ as $x \rightarrow \bar{x}$, such that:

$$f(x) = \underbrace{f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}) + \frac{1}{2} (x - \bar{x})^T \underline{H}(\bar{x}) (x - \bar{x})}_{\text{SO - approx}} + \underbrace{\|x - \bar{x}\|^2 \beta(x, \bar{x})}_{o(\|x - \bar{x}\|^2)}.$$

$$\underline{H}(\bar{x}) \triangleq \begin{bmatrix} \frac{\partial^2 f(\bar{x})}{\partial x_1^2} & \dots & \frac{\partial^2 f(\bar{x})}{\partial x_1 \partial x_n} \\ \vdots & & \vdots \\ \frac{\partial^2 f(\bar{x})}{\partial x_n \partial x_1} & \dots & \frac{\partial^2 f(\bar{x})}{\partial x_n^2} \end{bmatrix} \in \mathbb{R}^{n \times n}$$

3° A vector-valued fn f is diff'ble if each component is diff'ble. (twice)

A diff'ble vector-valued fn $h: \mathbb{R}^m \rightarrow \mathbb{R}^n$, the Jacobian, denoted by $\nabla \underline{h}(\underline{x})$, is given by the $n \times m$ matrix.

$$\underline{J}(\underline{x}) = \nabla \underline{h}(\underline{x}) = \begin{bmatrix} \nabla h_1(\underline{x})^T \\ \vdots \\ \nabla h_n(\underline{x})^T \end{bmatrix}_{n \times m}.$$



4° (MVT): S non-empty open convex set in \mathbb{R}^n , let $f: S \rightarrow \mathbb{R}$ be diff'ble. For every $\underline{x}_1, \underline{x}_2 \in S$, we have:
 $f(\underline{x}_2) = f(\underline{x}_1) + \nabla f(\underline{x})^T (\underline{x}_2 - \underline{x}_1)$, where $\underline{x} = \lambda \underline{x}_1 + (1-\lambda) \underline{x}_2$ for some $\lambda \in (0, 1)$.

5° Taylor's Thm. S non-empty, open, convex set in \mathbb{R}^n .

$f: S \rightarrow \mathbb{R}$, twice diff'ble. For every $\underline{x}_1, \underline{x}_2 \in S$, we have:

$$f(\underline{x}_2) = f(\underline{x}_1) + \nabla f(\underline{x})^T (\underline{x}_2 - \underline{x}_1) + \frac{1}{2} (\underline{x}_2 - \underline{x}_1)^T \underline{H}(\underline{x}) (\underline{x}_2 - \underline{x}_1),$$

where $\underline{H}(\underline{x})$ is Hessian at \underline{x} , and $\underline{x} = \lambda \underline{x}_1 + (1-\lambda) \underline{x}_2$, for some $\lambda \in (0, 1)$.

Linear Algebra:

1. Linear indep.: $\underline{x}_1, \dots, \underline{x}_k \in \mathbb{R}^n$ are lin. indep. if

$$\sum_{i=1}^k \lambda_i \underline{x}_i = \underline{0} \Rightarrow \lambda_i = 0, \forall i = 1, \dots, k.$$

2. linear comb.: $y \in \mathbb{R}^n$ is a lin. comb. of $x_1, \dots, x_k \in \mathbb{R}^n$ if

$$y = \sum_{i=1}^k \lambda_i x_i \quad \text{for some } \lambda_1, \dots, \lambda_k.$$

* $\sum_{i=1}^k \lambda_i = 1$: y is an affine comb. of x_1, \dots, x_k .

* $\sum_{i=1}^k \lambda_i = 1, \lambda_i \geq 0, \forall i$: y is a convex comb. of x_1, \dots, x_k .

The linear, affine, convex hull of $S \in \mathbb{R}^n$ are, resp., the set of all lin., affine, convex comb. of pts. in S .

3. Spanning vectors: $x_1, \dots, x_k \in \mathbb{R}^n, k \geq n$, said to be spanning \mathbb{R}^n if any vector in \mathbb{R}^n can be represented as lin. comb. of x_1, \dots, x_k .

The cone spanned by x_1, \dots, x_k is the set of non-neg. lin. ^{comb.}



4. Basis: A set of $x_1, \dots, x_k \in \mathbb{R}^n$ spans \mathbb{R}^n

and if the deletion of any of x_1, \dots, x_k prevents remaining vectors from spanning \mathbb{R}^n . (Basis x_1, \dots, x_k spans \mathbb{R}^n iff $k=n$).

5. Cauchy-Schwartz Ineq: $|\langle x, y \rangle| = |x^T y| \leq \|x\|_2 \|y\|_2$, with equality achieved iff x, y are lin dep.

(unsigned) angle btwn $x, y \in \mathbb{R}^n$.

$$\angle(x, y) \triangleq \cos^{-1} \left(\frac{x^T y}{\|x\|_2 \|y\|_2} \right) \in [0, \pi]$$

(x, y are orthogonal, $x \perp y$, if $\langle x, y \rangle = 0$)

6. Young's Ineq: $a > 0, b > 0$, and any $p, q > 0$ s.t. $\frac{1}{p} + \frac{1}{q} = 1$.
 we have $ab \leq \frac{a^p}{p} + \frac{b^q}{q}$, with eq. achieved iff $a^p = b^q$.
 (special case, $p = q = 2$).

7. Holder's Ineq: For any pair of vectors \underline{x} and $\underline{y} \in \mathbb{C}^n$, and for any p, q satisfying $\frac{1}{p} + \frac{1}{q} = 1$, we have:

$$\sum_{i=1}^n |x_i y_i| \leq \|\underline{x}\|_p \cdot \|\underline{y}\|_q.$$

(special case: $p = q = 2$, $p = 1, q = \infty$).

8. Orthogonal matrix: $\underline{Q} \in \mathbb{R}^{m \times n}$: $\underline{Q}^T \underline{Q} = \underline{I}_n$ or $\underline{Q} \underline{Q}^T = \underline{I}_m$.

If \underline{Q} is square: $\underline{Q}^T = \underline{Q}^{-1}$.

9. Rank of matrix: For $\underline{A} \in \mathbb{R}^{m \times n}$, $\text{rank}(\underline{A}) \triangleq$ max # of lin. indep. rows (or equivalently cols) of \underline{A} .

If $\text{rank}(\underline{A}) = \min\{m, n\}$, \underline{A} is full row/col rank.

10. Eigenvalues and eigenvectors: $\underline{A} \in \mathbb{R}^{n \times n}$. If λ and $\underline{x} \neq \underline{0}$ satisfy $\underline{A} \underline{x} = \lambda \underline{x}$, then λ and \underline{x} are eigenvalue & eigenvector.

* λ can be computed by solving $\det(\underline{A} - \lambda \underline{I}) = 0$ (characteristic eqn.).

* \underline{A} is symmetric \Rightarrow n (possibly non-distinct) real eigenvalues.

* Eigenvectors assoc. with distinct eigenvalues are orthogonal.

* Given some symmetric $\underline{A} \Rightarrow$ can construct an orthogonal basis $\underline{B} \in \mathbb{R}^{n \times r}$, where each col in \underline{B} is an eigenvector of \underline{A} .
 $r = \text{rank}$

* Normalize \underline{B} to have unit l_2 norm, s.t. $\underline{B}^T \underline{B} = \underline{I}$ ($\underline{B}^T = \underline{B}^{-1}$).

Then, \underline{B} is called orthonormal matrix.

* Let $\lambda_1 \dots \lambda_n$ be real eigenvalues of symmetric \underline{A}

$$\text{Let } \underline{\Lambda} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}. \quad \underline{A} \underline{B} = \underline{B} \underline{\Lambda}$$

$$\underline{A} \begin{bmatrix} | & & | \\ \underline{v}_1 & \dots & \underline{v}_n \\ | & & | \end{bmatrix} = \begin{bmatrix} | & & | \\ \underline{v}_1 & \dots & \underline{v}_n \\ | & & | \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$\stackrel{\underline{B}^T = \underline{B}^{-1}}{\Rightarrow} \underline{A} = \underline{B} \underline{\Lambda} \underline{B}^T = \sum_{i=1}^n \lambda_i \underline{b}_i \underline{b}_i^T$$

II. Singular - Value Decomp. (SVD).

Let $\underline{A} \in \mathbb{R}^{m \times n}$. Then $\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$, where $\underline{U} \in \mathbb{R}^{m \times m}$ orthonormal,

$\underline{V} \in \mathbb{R}^{n \times n}$ orthonormal, and $\underline{\Sigma} \in \mathbb{R}^{m \times n}$, $(\underline{\Sigma})_{ij} = 0$ for $i \neq j$.

$$(\underline{\Sigma})_{ii} \geq 0. \in \mathbb{R}$$

* Cols of \underline{U} : Normalized eigenvectors of $\underline{A} \underline{A}^T$

* Cols of \underline{V} : — — — — — of $\underline{A}^T \underline{A}$

* $(\underline{\Sigma})_{ii}$: Abs square root of eigenvalues of $\underline{A}^T \underline{A}$ if $m \leq n$
or $\underline{A} \underline{A}^T$ if $m \geq n$.

12. Definite & Semidefinite Matrices: $\underline{A} \in \mathbb{R}^{n \times n}$ symmetric.

\underline{A} is	PD	if	$\underline{x}^T \underline{A} \underline{x} > 0$, $\forall \underline{x} \neq 0, \underline{x} \in \mathbb{R}^n$
	PSD		≥ 0	, $\forall \underline{x} \in \mathbb{R}^n$
	ND		< 0	, $\forall \underline{x} \neq 0, \underline{x} \in \mathbb{R}^n$
	NSD		≤ 0	, $\forall \underline{x} \in \mathbb{R}^n$

\underline{A} is indef. if neither PSD nor NSD.

\underline{A} is	PD	if eigenvalues are	pos.
	PSD		non-neg. , resp.
	ND		neg.
	NSD		non-pos.

13. If \underline{A} is PSD, \underline{A}^{\pm} is the matrix satisfying

$$\underline{A}^{\pm} \cdot \underline{A}^{\pm} = \underline{A}, \text{ and } \underline{A}^{\pm} = \underline{B} \underline{\Lambda}^{\pm} \underline{B}^T$$

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$$\begin{bmatrix} \lambda_1^{\pm} & & 0 \\ & \ddots & \\ 0 & & \lambda_n^{\pm} \end{bmatrix}$$