

Math Background Review

Basic Analysis:

A. Norm: A fn $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is called norm if:

* (non-neg.) : $f(x) \geq 0, \forall x \in \mathbb{R}^n, f(x) = 0 \iff x = 0$

* (homogeneity): $f(tx) = |t|f(x), \forall x \in \mathbb{R}^n, t \in \mathbb{R}$.

* (triangle ineq.): $f(x+y) \leq f(x) + f(y), \forall x, y \in \mathbb{R}^n$

If $f(x)$ is a norm, denote it as $\|x\|$.

2. Norm $\|x\|$'s meaning:

* $\|x\|$ = length of x .

* $\|x-y\|$ = dist. btwn x & y .

3. Unit ball: Set of vectors with $\|x\| \leq 1$.

$$B = \{x \in \mathbb{R}^n : \|x\| \leq 1\}$$

Ex: * l_2 -norm (Euclidean Norm): $\|x\|_2 \triangleq (x^T x)^{\frac{1}{2}} = (x_1^2 + \dots + x_n^2)^{\frac{1}{2}}$

* l_1 -norm (sum-abs-val.): $\|x\|_1 \triangleq |x_1| + \dots + |x_n|$ (Manhattan dist.)

* l_∞ -norm (Chebyshev): $\|x\|_\infty \triangleq \max\{|x_1|, \dots, |x_n|\}$

* l_p -norm: $\|x\|_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}}$ Q: $\|x\|_\infty \stackrel{?}{=} \lim_{p \rightarrow \infty} \|x\|_p$

$$\begin{aligned} \text{Proof: } \|x\|_p &= \frac{(|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}}}{\left(\frac{|x_1|^p}{\|x\|_\infty^p} + \dots + \frac{|x_n|^p}{\|x\|_\infty^p}\right)^{\frac{1}{p}}} \|x\|_\infty \\ &\leq (1 + \dots + 1)^{\frac{1}{p}} \|x\|_\infty = \sqrt[p]{n} \|x\|_\infty \end{aligned}$$

Let $i^* \in \arg \max_i \{|x_i|\}$

$$\geq (|x_{i^*}|^p)^{\frac{1}{p}} = |x_{i^*}| = \|x\|_\infty$$

Let $p \rightarrow \infty, \sqrt[p]{n} \rightarrow 1$ (squeeze thm)



Equivalence of Norm:

Suppose $\|\cdot\|_a$ and $\|\cdot\|_b$ are norms on \mathbb{R}^n , then $\exists \alpha, \beta > 0$

$$\text{s.t. } \forall x \in \mathbb{R}^n, \quad \alpha \|x\|_a \leq \|x\|_b \leq \beta \|x\|_a.$$

$$\text{Ex: } \|x\|_2 \leq \|x\|_1 \leq \sqrt{n} \|x\|_2.$$

$$\|x\|_\infty \leq \|x\|_2 \leq \sqrt{n} \|x\|_\infty$$

$$\|x\|_\infty \leq \|x\|_1 \leq n \|x\|_\infty$$

4. Convergent Sequence & Limits

1° Def (Convergence): A seq. of vectors x_1, x_2, \dots are said to be convergent to a limit pt. \bar{x} , if $\forall \epsilon > 0, \exists N_\epsilon \in \mathbb{N}$

$$\text{s.t. } \|x_k - \bar{x}\| < \epsilon, \forall k \geq N_\epsilon \quad (\{x_k\} \rightarrow \bar{x} \text{ as } k \rightarrow \infty, \lim_{k \rightarrow \infty} x_k = \bar{x})$$

2° Def (Cauchy seq.): A seq. $\{x_k\}$ is Cauchy if

$$\forall \epsilon > 0, \exists N \in \mathbb{N}, \text{ s.t. } \|x_m - x_n\| < \epsilon, \forall m, n > N$$

Thm: A seq. in \mathbb{R}^n has a limit iff it's Cauchy.

Ex: (p-series): $a_n = \frac{1}{n^p}$. Show $\{b_n\} = \left\{ \sum_{k=1}^n a_k \right\}$ has a limit for $p > 1$.

Also, $\{b_n\}$ doesn't converge for $p = 1$.

Proof. w.l.o.g. let $m, n \in \mathbb{N}$ and $m < n$.

$$1. p=2: \quad b_n - b_m = \sum_{k=1}^n \frac{1}{k^2} - \sum_{k=1}^m \frac{1}{k^2} = \sum_{k=m+1}^n \frac{1}{k^2} < \sum_{k=m+1}^n \frac{1}{k(k-1)}$$

$$= \sum_{k=m+1}^n \left(\frac{1}{k-1} - \frac{1}{k} \right) = \frac{1}{m} - \frac{1}{m+1} + \frac{1}{m+1} - \frac{1}{m+2} \dots - \frac{1}{n} = \frac{1}{m} - \frac{1}{n}$$

$< \frac{1}{m} < \epsilon$ I can always find suff. large m s.t. $b_n - b_m < \epsilon$

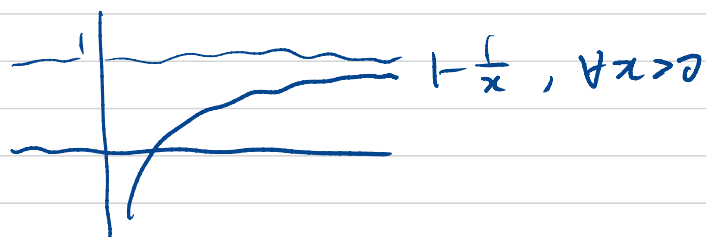
harmonic series

2. $p=1$: $b_n - b_m = \sum_{k=1}^n \frac{1}{k} - \sum_{k=1}^m \frac{1}{k} = \sum_{k=m+1}^n \frac{1}{k} = \underbrace{\frac{1}{m+1}}_{> \frac{1}{n}} + \dots + \frac{1}{n}$

$$> \frac{n-m}{n} = 1 - \frac{m}{n}$$

\Rightarrow For any $\epsilon > 0$, for any m (no matter how large m is), can choose $n \geq \lceil \frac{m}{1-\epsilon} \rceil$, s.t. $|b_n - b_m| > \epsilon$.

5. Supremum of S (least UB): Smallest possible α : $\alpha \geq x, \forall x \in S$.



Infimum of S (largest LB): largest possible value $\alpha \leq x, \forall x \in S$.



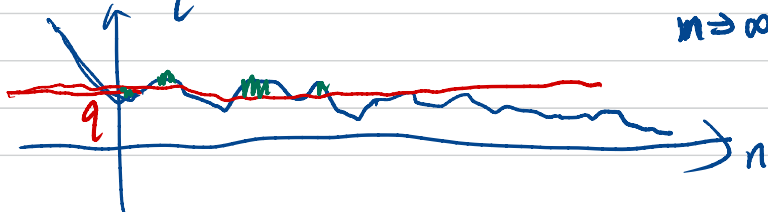
6. Maximum, Minimum: (achievable).

* The limit supremum $\limsup_{k \rightarrow \infty} x_k$ is the infimum of all

$q \in \mathbb{R}$ for which all but a finite # of elements in $\{x_k\}$

exceed q .

$$\limsup_{n \rightarrow \infty} x_n \triangleq \lim_{n \rightarrow \infty} \left\{ \sup_{m \geq n} x_m \right\}$$



* The limit infimum $\liminf_{k \rightarrow \infty} x_k$ is the supremum of all $q \in \mathbb{R}$ for which all but a finite # of elements in $\{x_k\}$ less than q .

$$\liminf_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} \left\{ \inf_{m \geq n} x_m \right\}$$

* \limsup & \liminf always exist.

* $\{x_n\}$ converge $\iff \limsup_{n \rightarrow \infty} x_n = \liminf_{n \rightarrow \infty} x_n$.

3. Functions.

1° Cont. fn: A fn $f: S \rightarrow \mathbb{R}$ is cont. at $\bar{x} \in S$ if $\forall \epsilon > 0, \exists \delta > 0$, s.t. $\forall x \in S$, with $\|x - \bar{x}\| < \delta \rightarrow |f(x) - f(\bar{x})| < \epsilon$.

write: $f(x) \rightarrow f(\bar{x})$, as $x \rightarrow \bar{x}$.

Fact: cont. fn achieves both maximum & minimum over a non-empty compact set.
closed & bounded.



2. Diff'ble fn:

a) S non-empty set in \mathbb{R}^n , $\bar{x} \in \text{int } S$. Given $f: S \rightarrow \mathbb{R}$.

f is diff'ble at \bar{x} if \exists a vector (called gradient)

$$\nabla f(\bar{x}) \triangleq \left[\frac{\partial f(\bar{x})}{\partial x_1} \quad \dots \quad \frac{\partial f(\bar{x})}{\partial x_n} \right]^T \text{ at } \bar{x} \text{ and } \exists \text{ fn}$$

$\beta(x, \bar{x}) \rightarrow 0$ as $x \rightarrow \bar{x}$, s.t.

$$f(x) = \underbrace{f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x})}_{\text{FO - approx. (linear approx)}} + \underbrace{\|x - \bar{x}\| \beta(x, \bar{x})}_{o(\|x - \bar{x}\|)}, \forall x \in S.$$



(2) f is called twice diff'ble at \bar{x} if, in addition to grad, \exists a symmetric $n \times n$ matrix $\underline{H}(\bar{x})$ (called Hessian matrix) of f at \bar{x} , and $\beta(x, \bar{x}) \rightarrow 0$ as $x \rightarrow \bar{x}$, s.t.

$$f(x) = \underbrace{f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}) + \frac{1}{2} (x - \bar{x})^T \underline{H}(\bar{x}) (x - \bar{x})}_{\text{so - approx.}} + \underbrace{\|x - \bar{x}\|^2 \beta(x, \bar{x})}_{o(\|x - \bar{x}\|^2)}$$

$$\underline{H}(x) \triangleq \begin{bmatrix} \frac{\partial^2 f(x)}{\partial x_1^2} & \dots & \frac{\partial^2 f(x)}{\partial x_1 \partial x_n} \\ \vdots & & \vdots \\ \frac{\partial^2 f(x)}{\partial x_n \partial x_1} & \dots & \frac{\partial^2 f(x)}{\partial x_n^2} \end{bmatrix}$$

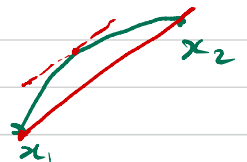
3° A vector-valued fn f is diff'ble if each component is diff'ble (twice).

A diff'ble vector-valued fn: $h: \mathbb{R}^m \rightarrow \mathbb{R}^n$, The Jacobian

$\underline{J}(x) = \nabla \underline{h}(x)$ is a $n \times m$ matrix:

$$\underline{J}(x) = \nabla \underline{h}(x) = \begin{bmatrix} \nabla h_1(x)^T \\ \vdots \\ \nabla h_n(x)^T \end{bmatrix}_{n \times m}$$

Hessian is a special case of Jacobian.



4° (MVT): S nonempty open convex set in \mathbb{R}^n . Let $f: S \rightarrow \mathbb{R}$

be diff'ble. For every $x_1, x_2 \in S$, we have

$$f(x_2) = f(x_1) + \nabla f(\bar{x})^T (x_2 - x_1), \text{ where } \bar{x} = \lambda x_1 + (1 - \lambda)x_2$$

for some $\lambda \in (0, 1)$.

5° Taylor's Thm: S non-empty, open, convex in \mathbb{R}^n .

$f: S \rightarrow \mathbb{R}$, twice diffble. For every $x_1, x_2 \in S$, we have:

$$f(x_2) = f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{1}{2} (x_2 - x_1)^T \underbrace{H_f(x)}_{\text{Hessian}} (x_2 - x_1).$$

Linear Algebra:

1. linear indep: $x_1, \dots, x_k \in \mathbb{R}^n$ are lin. indep. if

$$\sum_{i=1}^k \lambda_i x_i = 0 \Rightarrow \lambda_i = 0, \forall i = 1, \dots, k.$$

2. linear comb: $y \in \mathbb{R}^n$ is lin. comb. of $x_1, \dots, x_k \in \mathbb{R}^n$ if

$$y = \sum_{i=1}^k \lambda_i x_i \text{ for some } \lambda_1, \dots, \lambda_k \in \mathbb{R}.$$

* $\sum_{i=1}^k \lambda_i = 1$: y is an affine comb. of x_1, \dots, x_k .

* $\sum_{i=1}^k \lambda_i = 1, \lambda_i \geq 0, \forall i$: y is a convex comb. of x_1, \dots, x_k .

The linear, affine, convex hulls of $S \subseteq \mathbb{R}^n$ are, resp., the sets of all lin. affine, convex comb. of pts. in S .

3. Spanning vectors: $x_1, \dots, x_k \in \mathbb{R}^n, k \geq n$ are said to be spanning \mathbb{R}^n if any vector in \mathbb{R}^n can be represented as a lin. comb. of x_1, \dots, x_k .



The cone spanned by x_1, \dots, x_k is set of non-neg. lin. comb.

4. Basis: A minimal set of $\underline{x}_1, \dots, \underline{x}_k \in \mathbb{R}^n$ spans \mathbb{R}^n . If the deletion of any of $\underline{x}_1, \dots, \underline{x}_k$ prevents remaining vectors from spanning \mathbb{R}^n . (Basis $\underline{x}_1, \dots, \underline{x}_k$ spans \mathbb{R}^n iff $k=n$).

5. Cauchy-Schwartz Ineq: $|\langle \underline{x}, \underline{y} \rangle| = |\underline{x}^T \underline{y}| \leq \|\underline{x}\|_2 \cdot \|\underline{y}\|_2$.

(unsigned angle btwn $\underline{x}, \underline{y} \in \mathbb{R}^n$.)

↑ with eq. achieved iff $\underline{x}, \underline{y}$ are lin. dep.

$$\angle(\underline{x}, \underline{y}) \triangleq \cos^{-1} \left(\frac{\underline{x}^T \underline{y}}{\|\underline{x}\|_2 \cdot \|\underline{y}\|_2} \right) \in [0, \pi]$$

cos. sim.

\underline{x} and \underline{y} are orthogonal, i.e., $\underline{x} \perp \underline{y}$ if $\langle \underline{x}, \underline{y} \rangle = 0$. conjugate

Young's Inq: For $a > 0, b > 0$, and any $p, q > 0$ s.t. $\frac{1}{p} + \frac{1}{q} = 1$ we have $ab \leq \frac{a^p}{p} + \frac{b^q}{q}$, with eq. achieved iff $a^p = b^q$.

(special cases: $p=q=2, p(\text{or } q)=1, q(\text{or } p)=\infty$).

Holder's Ineq: For any pair of vec. $\underline{x}, \underline{y} \in \mathbb{R}^n$, and for p, q s.t.

$$\frac{1}{p} + \frac{1}{q} = 1, \text{ we have: } \sum_{i=1}^n |x_i y_i| \leq \|\underline{x}\|_p \cdot \|\underline{y}\|_q$$

$$= \|\underline{x} \circ \underline{y}\|_1 \quad (\text{Holder's} \Rightarrow \text{Cauchy-Schwarz})$$

6. Orthogonal matrix: $\underline{Q} \in \mathbb{R}^{m \times n}$. $\underline{Q}^T \underline{Q} = \underline{I}_n$ or $\underline{Q} \underline{Q}^T = \underline{I}_m$.

$(m \geq n)$ $(n \geq m)$

If \underline{Q} is square: $\underline{Q}^{-1} = \underline{Q}^T$.

7. Rank of matrix: For $\underline{A} \in \mathbb{R}^{m \times n}$, $\text{rank}(\underline{A}) = \max \#$ of lin. indep. rows (or equivalently, cols) of \underline{A} .

If $\text{rank}(\underline{A}) = \min \{m, n\}$, \underline{A} is full row/col rank.

8. Eigenvalues and Eigenvectors: $\underline{A} \in \mathbb{R}^{n \times n}$. If λ and $\underline{x} \neq \underline{0}$ satisfy: $\underline{A}\underline{x} = \lambda\underline{x}$, then λ, \underline{x} are eigenvalues & eigenvector.

* λ can be computed by solving $\det(\underline{A} - \lambda \underline{I}) = 0$.

* \underline{A} is symmetric $\Rightarrow n$ (possibly non-distinct) real eigenvalues multiplicity.

* Eigenvectors assoc. with distinct eigenvalues are orthogonal.

* Given symmetric $\underline{A} \Rightarrow$ can construct basis $\underline{B} \in \mathbb{R}^{n \times n}$.

where each col in \underline{B} is an eigenvector of \underline{A} .

* Normalize \underline{B} to have unit ℓ_2 -norm: s.t. $\underline{B}^T \underline{B} = \underline{I}$ ($\underline{B}^T = \underline{B}^{-1}$).

Then \underline{B} is called orthonormal matrix.

Eigen-decomp: $\underline{A} = \underline{B} \underline{\Lambda} \underline{B}^T$.

9. Singular-Value Decomp. (SVD):

Let $\underline{A} \in \mathbb{R}^{m \times n}$. Then $\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$, where $\underline{U} \in \mathbb{R}^{m \times m}$ orthonormal,

$\underline{V} \in \mathbb{R}^{n \times n}$ orthonormal, $\underline{\Sigma} \in \mathbb{R}^{m \times n}$, $(\underline{\Sigma})_{ij} = 0$, for $\forall i \neq j$.

$(\underline{\Sigma})_{ii} \geq 0$
 $\in \mathbb{R}$.

* Gols of \underline{U} : Normalized eigenvectors of $\underline{A}\underline{A}^T$

* \underline{V} : $\underline{A}^T \underline{A}$

* $(\underline{\Sigma})_{ii}$: Abs. square root of eigenvalues of $\underline{A}\underline{A}^T$ if $m \geq n$,
or $\underline{A}^T \underline{A}$ if $m < n$.

12. Definite & Semidefinite Matrices : $\underline{A} \in \mathbb{R}^{n \times n}$ symmetric.

	PD	$x^T \underline{A} x > 0$	$\forall x \neq 0, x \in \mathbb{R}^n$
\underline{A} is	PSD	≥ 0	$\forall x \in \mathbb{R}^n$
	ND	< 0	$\forall x \neq 0, x \in \mathbb{R}^n$
	NSD	≤ 0	$\forall x \in \mathbb{R}^n$

\underline{A} is indef. if neither PSD nor NSD.

	PD	pos.
\underline{A} is	PSD	non-neg.
	ND	neg.
	NSD	non-pos.

if eigenvalues are

If \underline{A} is PSD, then $\underline{A}^{\frac{1}{2}}$ is the matrix satisfying

$$\underline{A}^{\frac{1}{2}} \underline{A}^{\frac{1}{2}} = \underline{A} \quad \text{and} \quad \underline{A}^{\frac{1}{2}} = \underline{B} \underline{\Lambda}^{\frac{1}{2}} \underline{B}^T$$

\nwarrow $\left[\lambda_1^{\frac{1}{2}} \quad \dots \quad \lambda_n^{\frac{1}{2}} \right]$